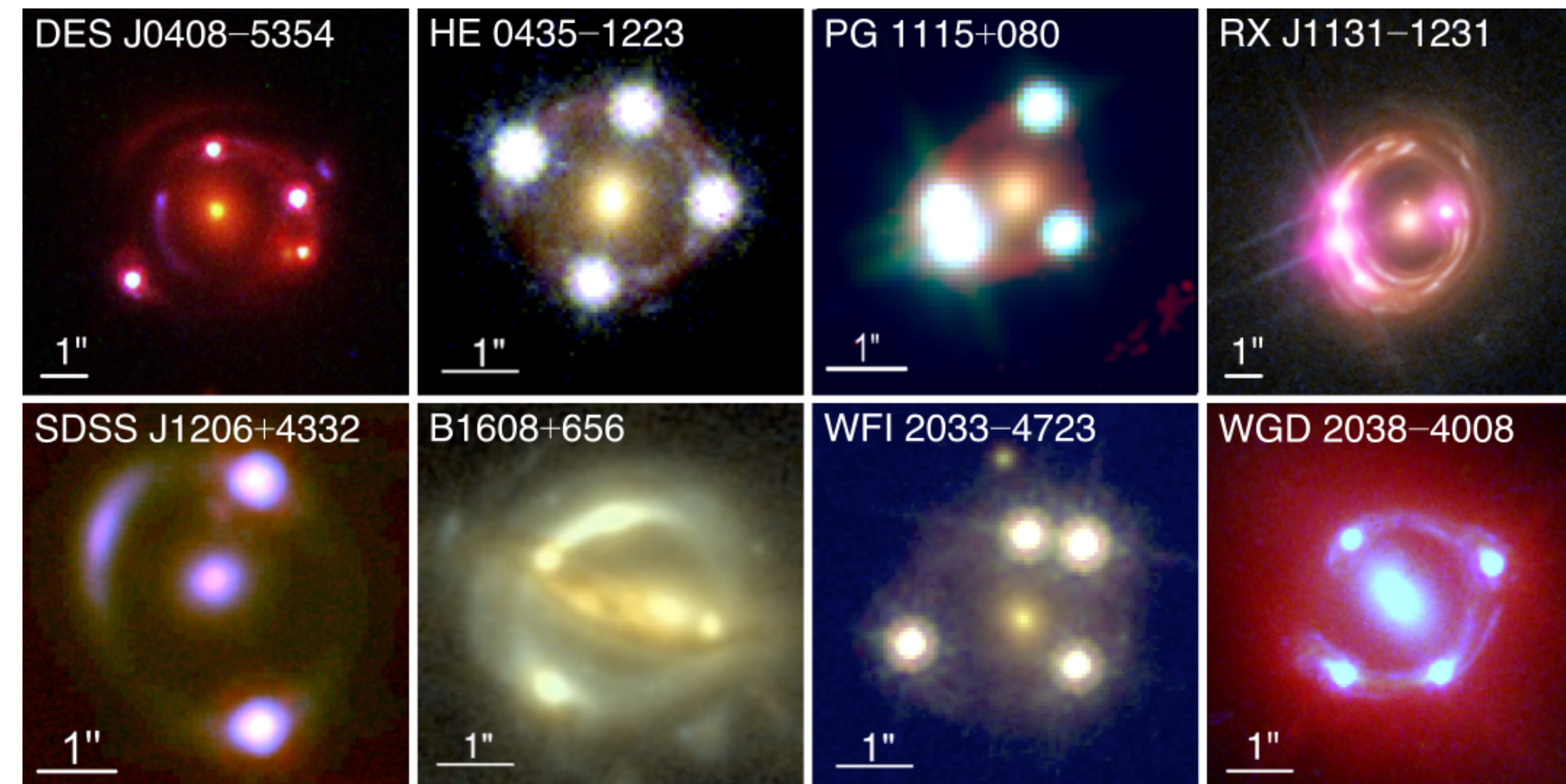


Precision kinematics of lens galaxy for precision measurement of H_0 using time-delay cosmography



Pritom Mozumdar

University of California, Los Angeles

with

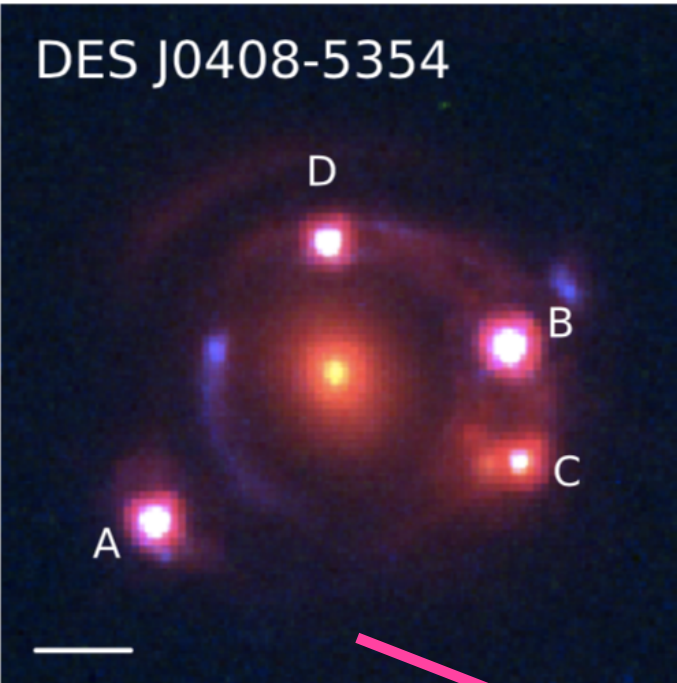
TDCOSMO collaboration

Outline :

- Why kinematics is integral for precision H_0 - a tale of two degeneracies.
- How to improve precision on measured kinematics?
 - Improving random error budget
 - Improving systematic error budget

Recap: Measuring H_0 using time-delay cosmography

Hi-resolution
imaging



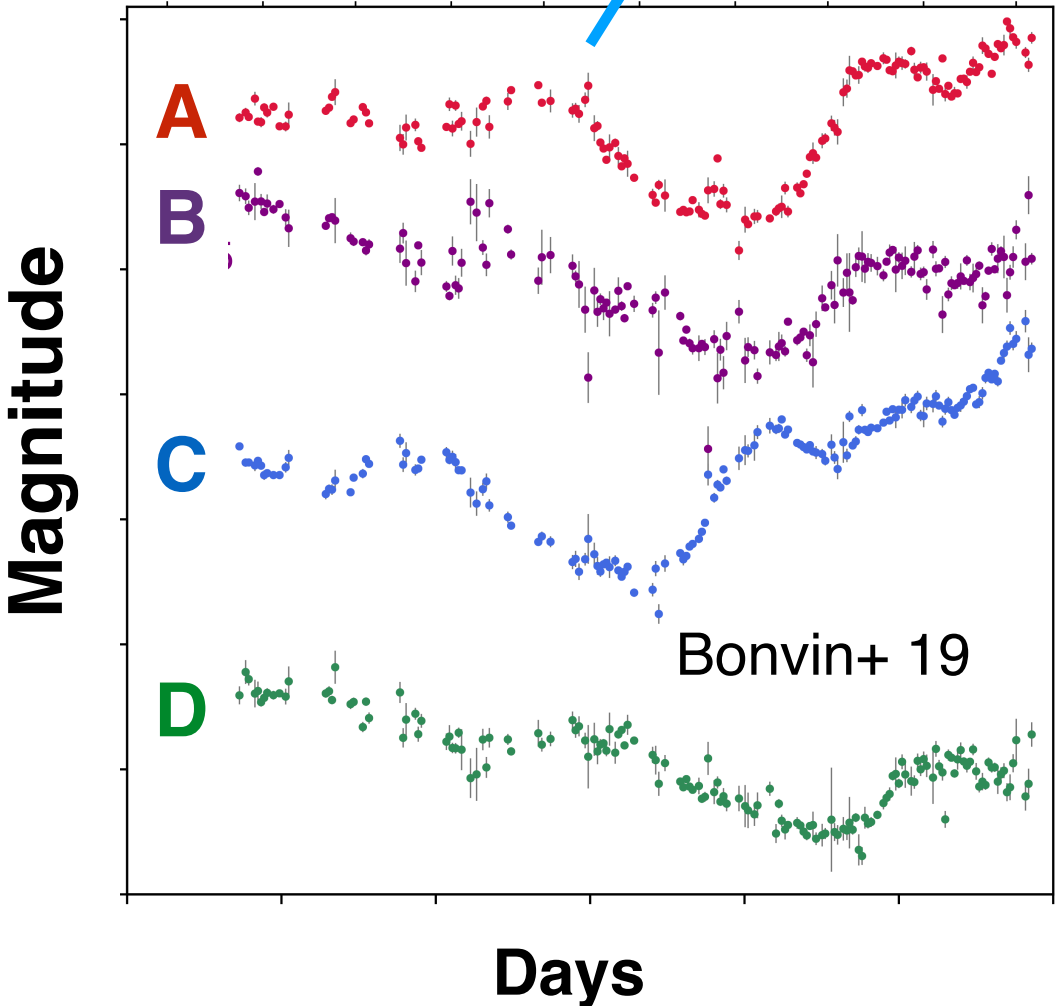
Fermat potential difference

Treu & Shajib (2023)

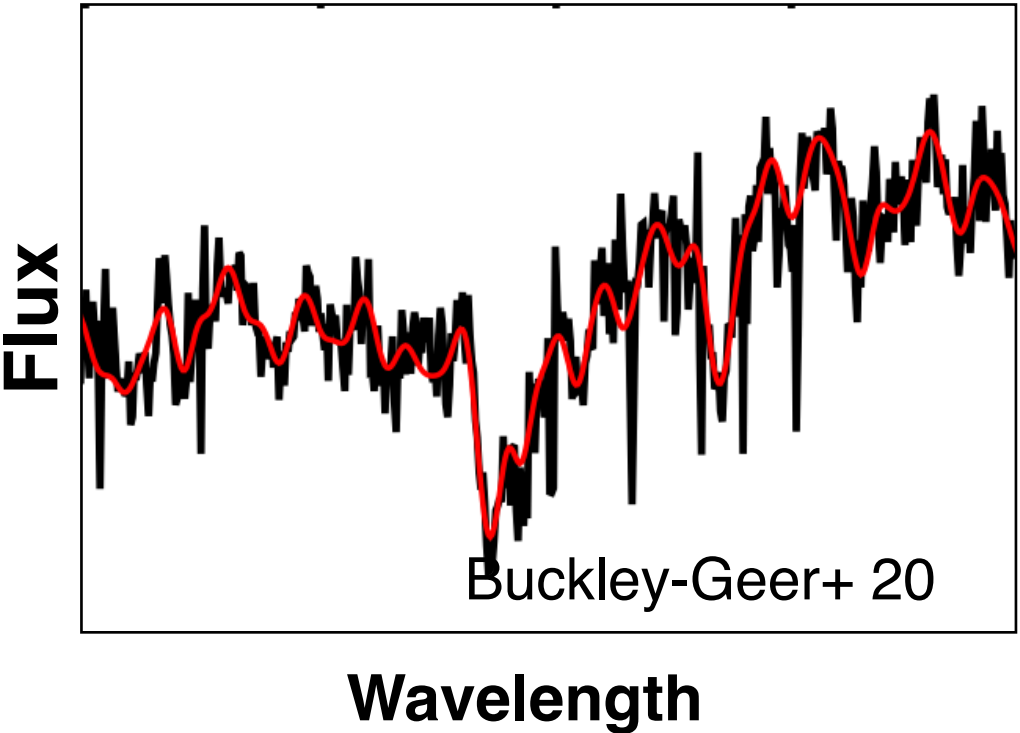
$$H_0 = \frac{\Delta \tau_{\text{model}} (1 - \kappa_{\text{ext}}) \lambda_{\text{int}} f_k(0, z_d, \Theta) f_k(0, z_s, \Theta)}{\Delta t f_k(z_d, z_s, \Theta)}$$

Time delays

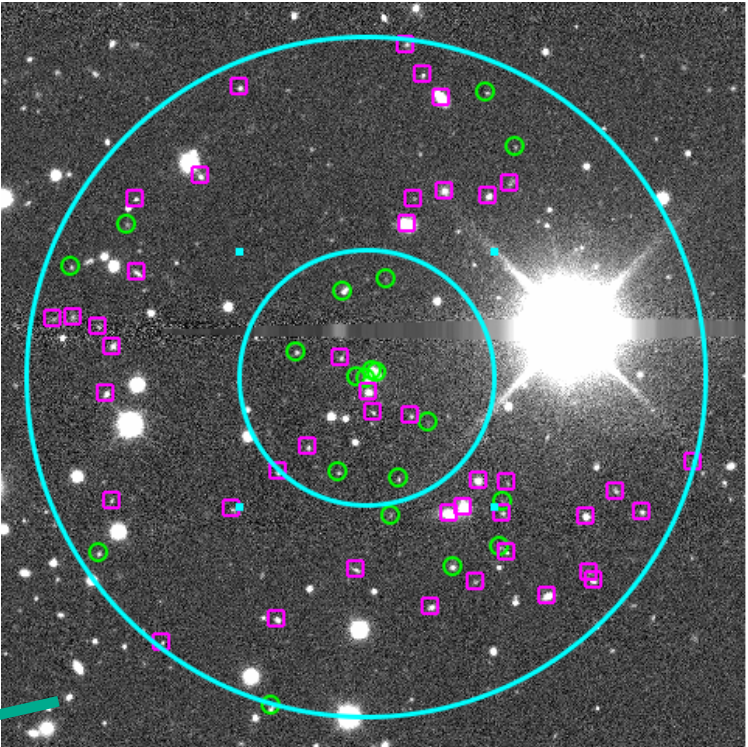
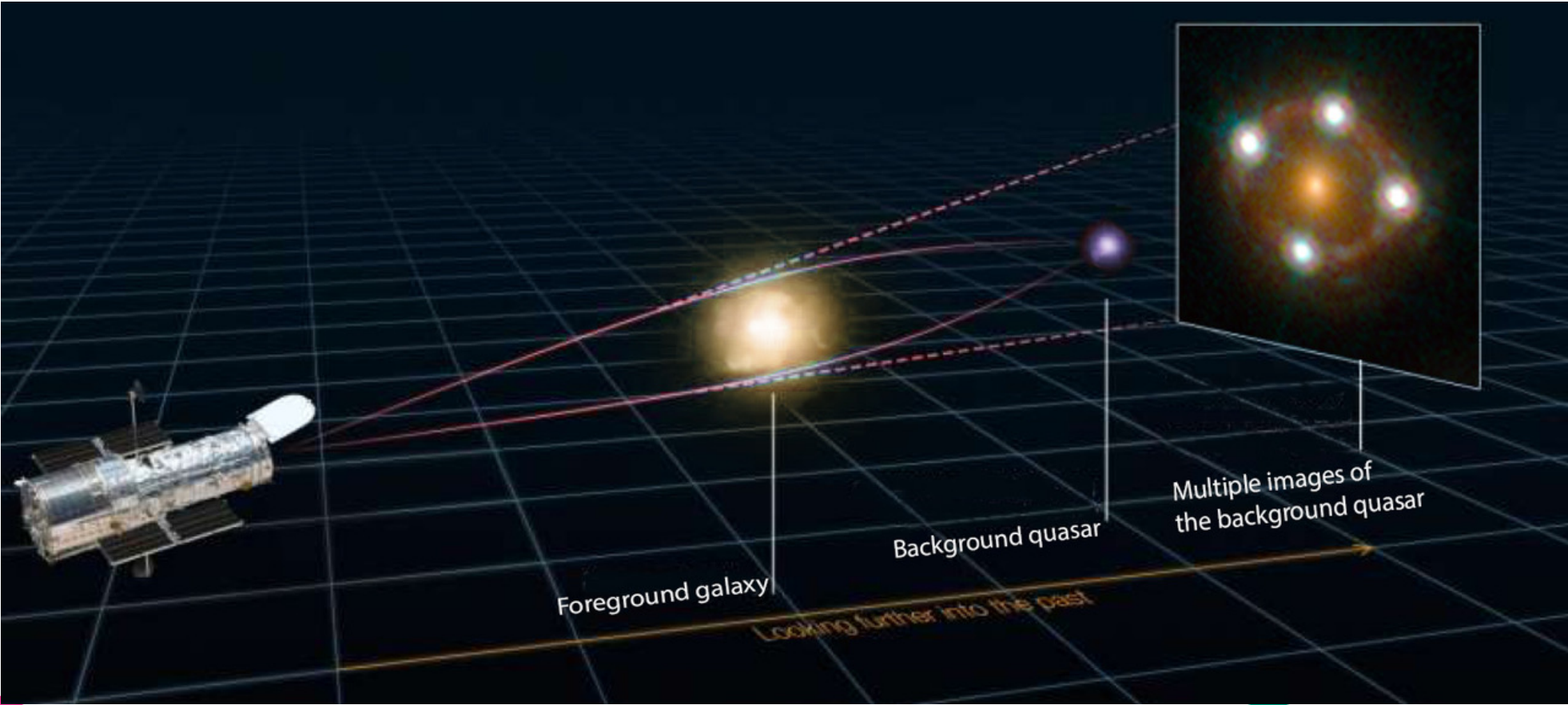
Long-term monitoring
with 1- or 2-m
telescopes



Deviation from mass model parametrization



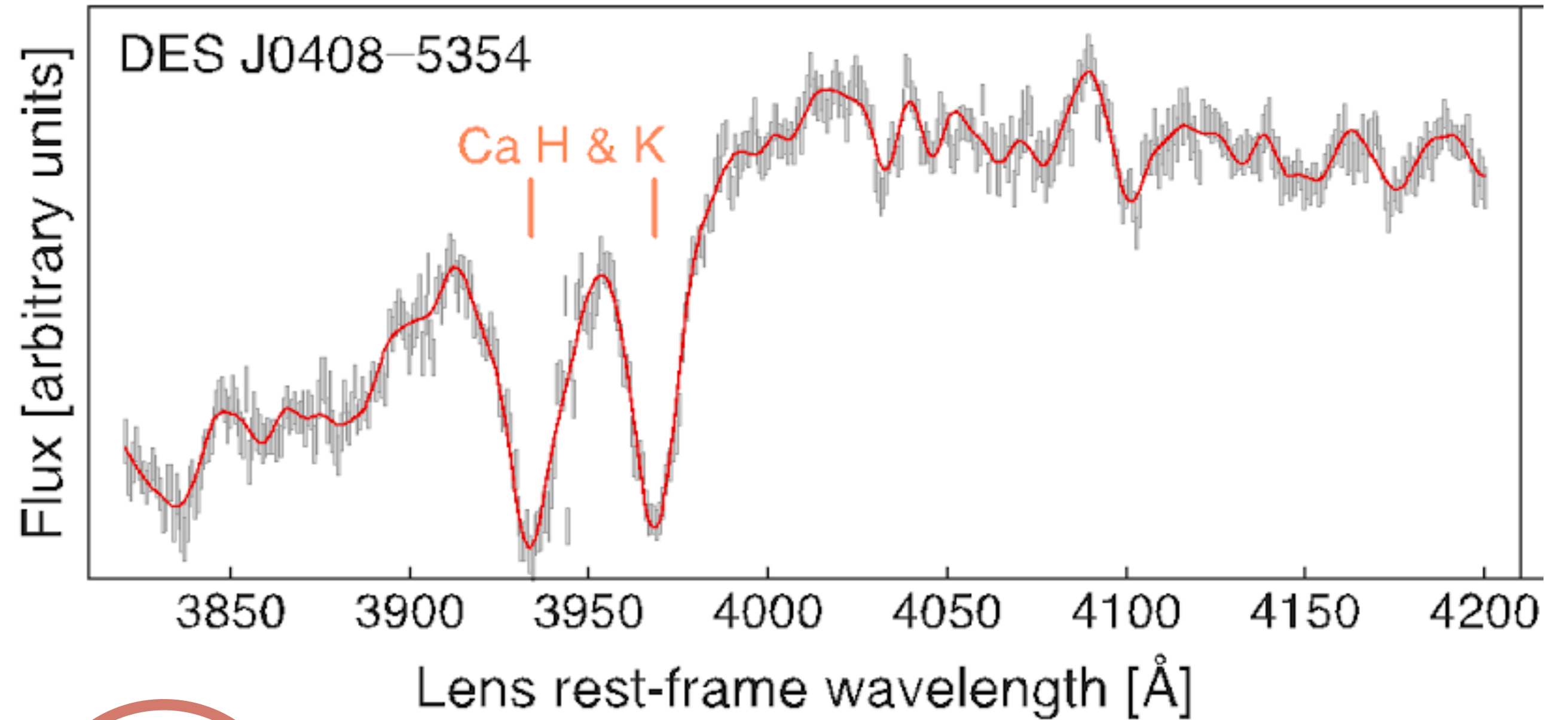
Ground/Space based
Slit/IFU spectroscopy



Photometric survey,
spectroscopic survey,
N-body simulation

We need 4 ingredients to infer H_0 :

- Time Delays Measurement
- Lens Modelling
- External Convergence
- Stellar kinematics

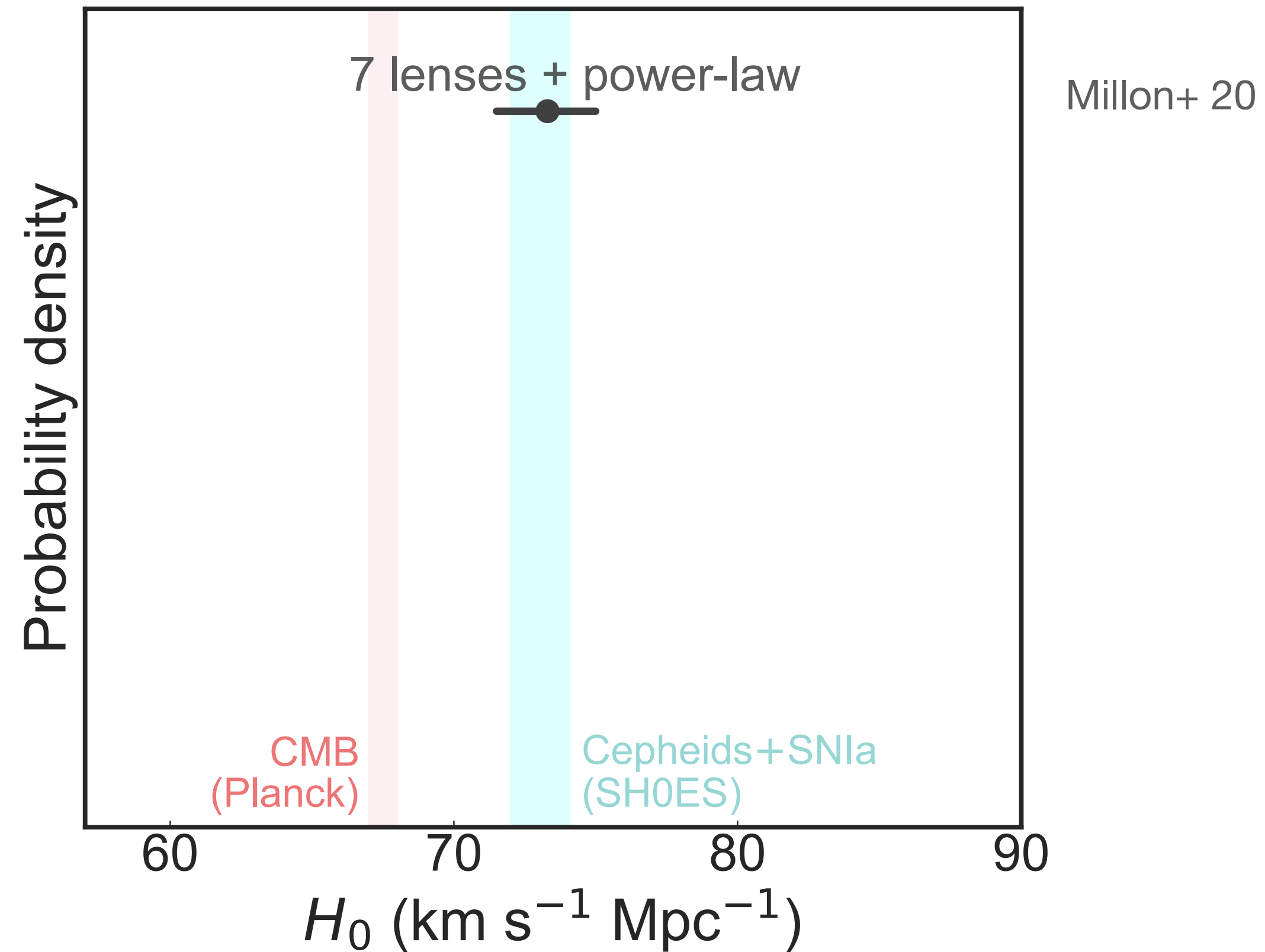


$$H_0 = \frac{\Delta\Phi_{\text{model}}(1 - \kappa_{\text{ext}})\lambda_{\text{int}}}{\Delta t} f(z_d, z_s, \Omega_m, \Omega_s, \dots)$$

From lens galaxy spectra and dynamical modeling

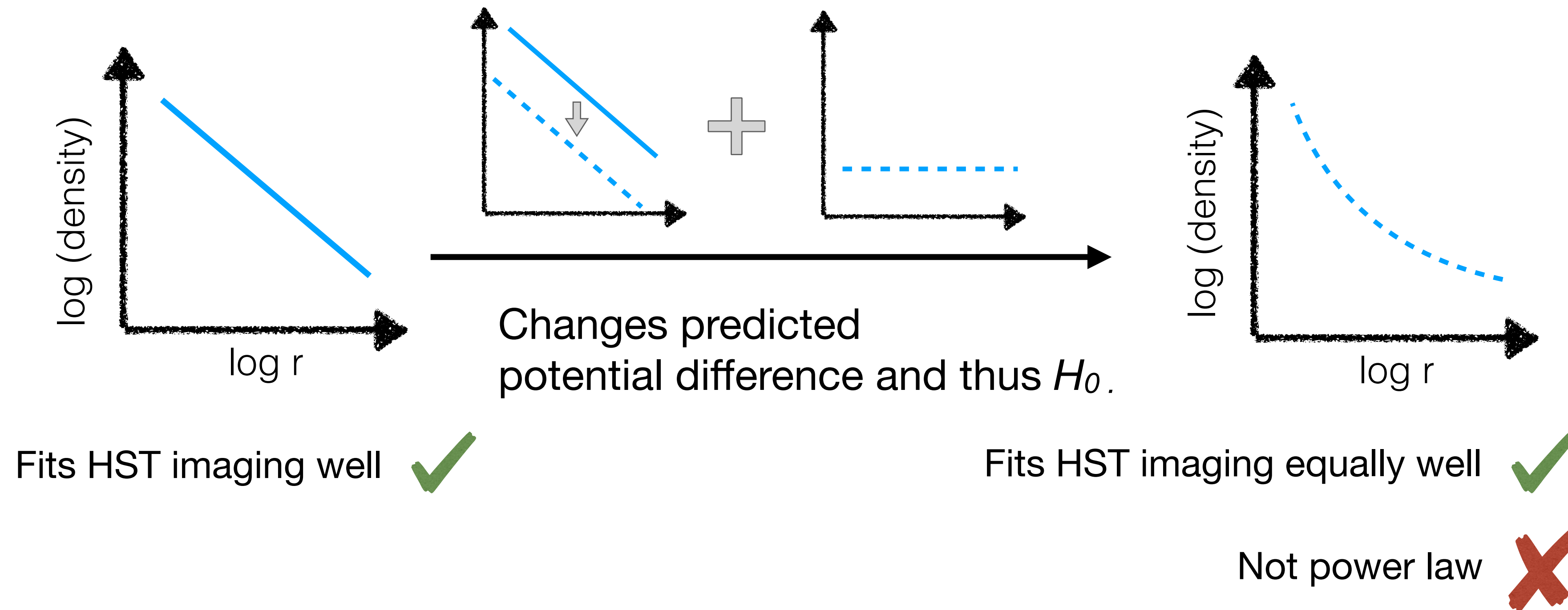
Lensing-only perspective of the Hubble tension

Λ CDM model (Cosmology) $\longleftrightarrow$? Power-law mass model (Astrophysics)



Mass-sheet degeneracy (MSD) in lensing

$$\Sigma \rightarrow \Sigma' = \lambda \Sigma + (1 - \lambda)$$

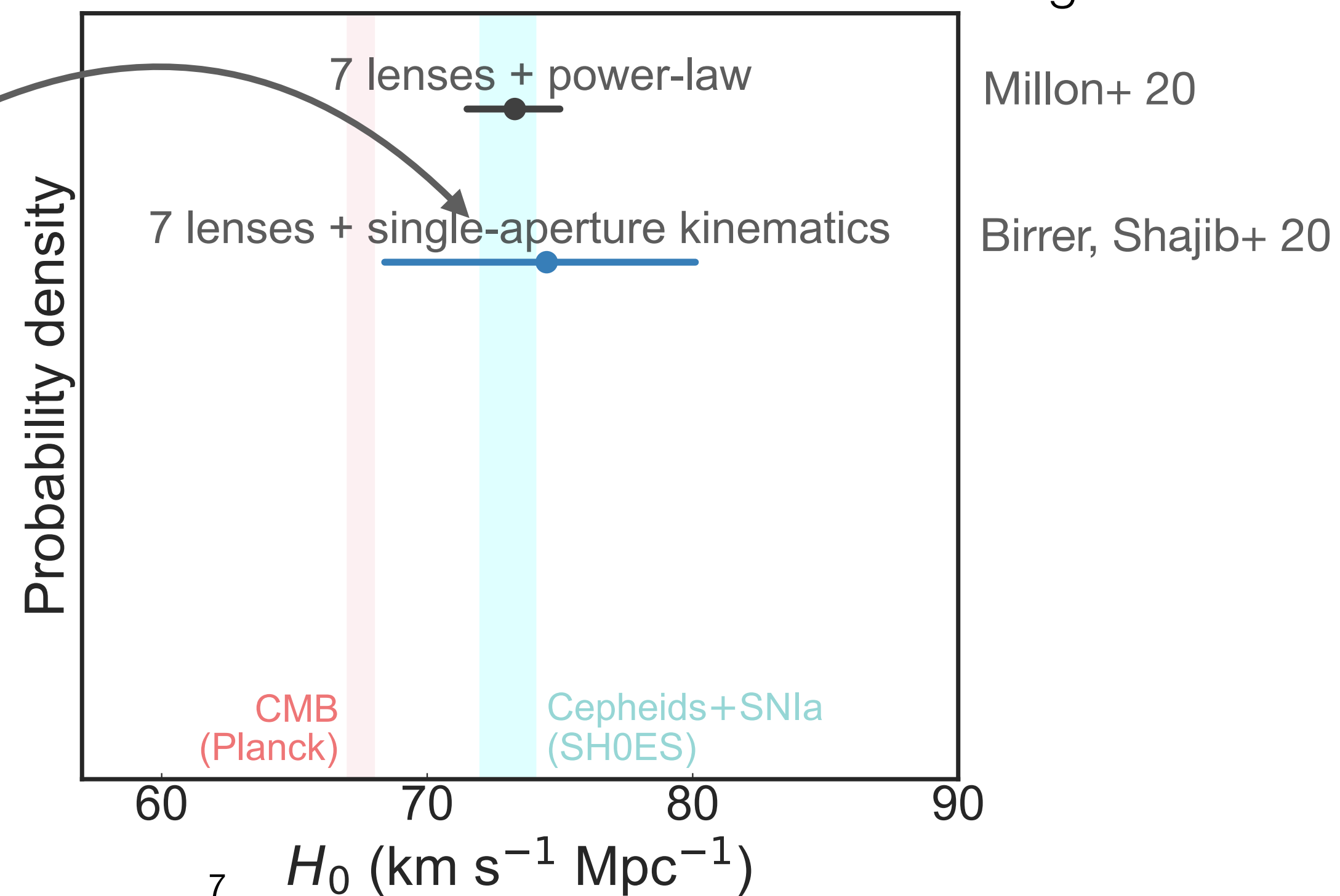
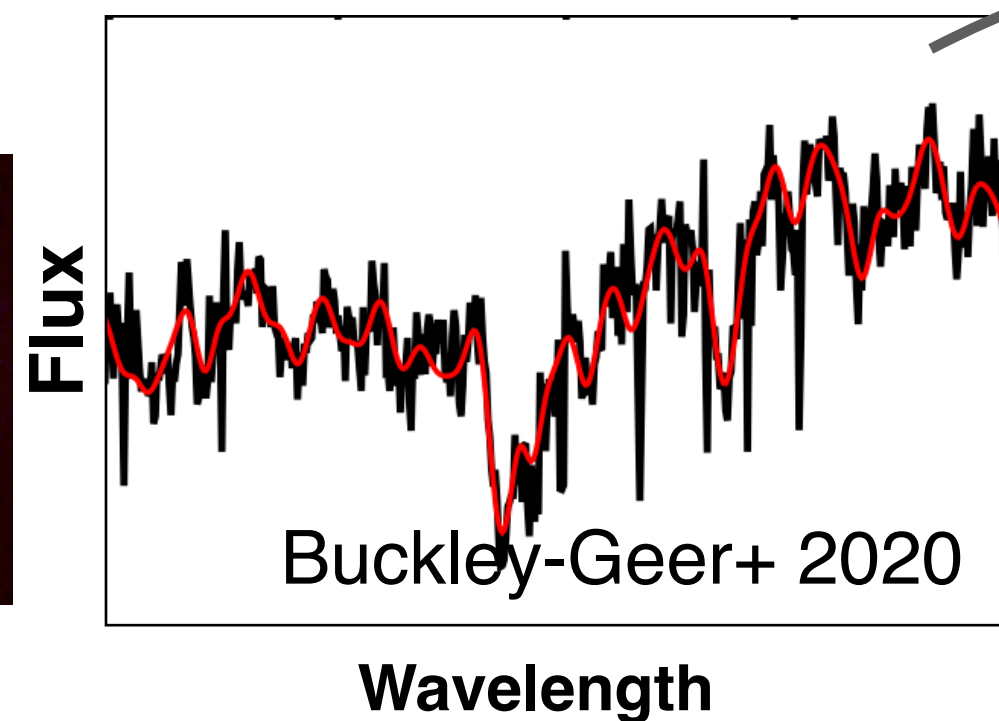
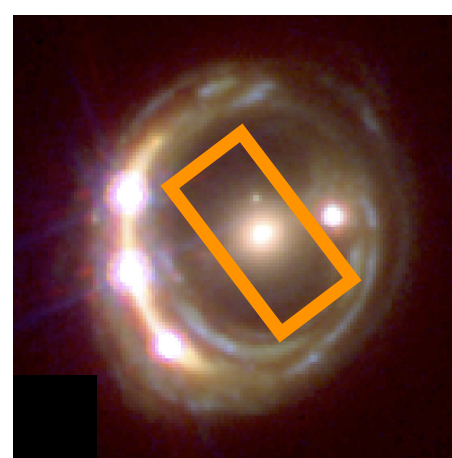
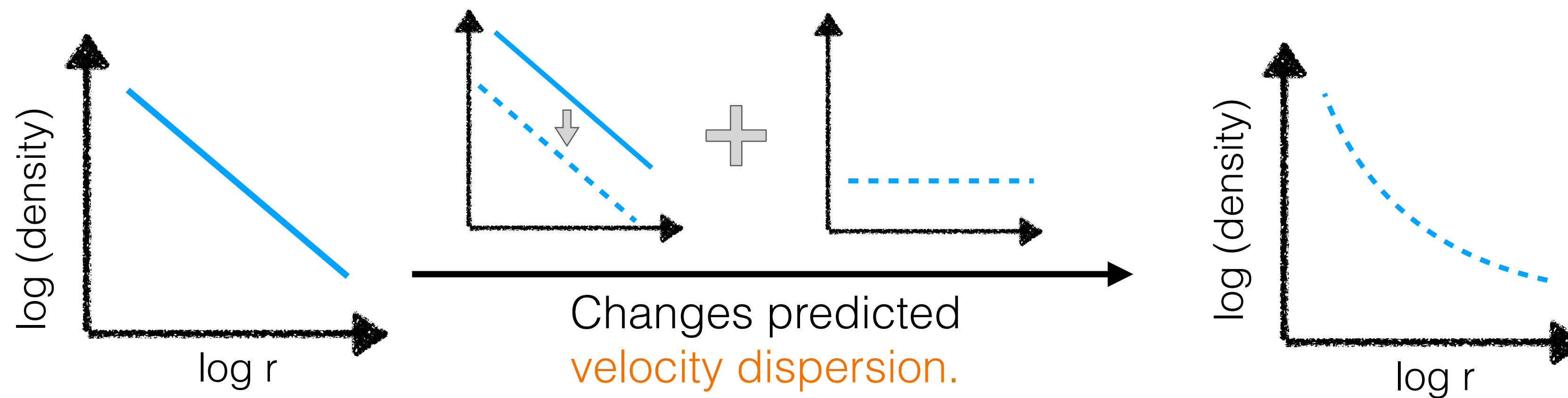


Power-law model implicitly breaks the MSD.

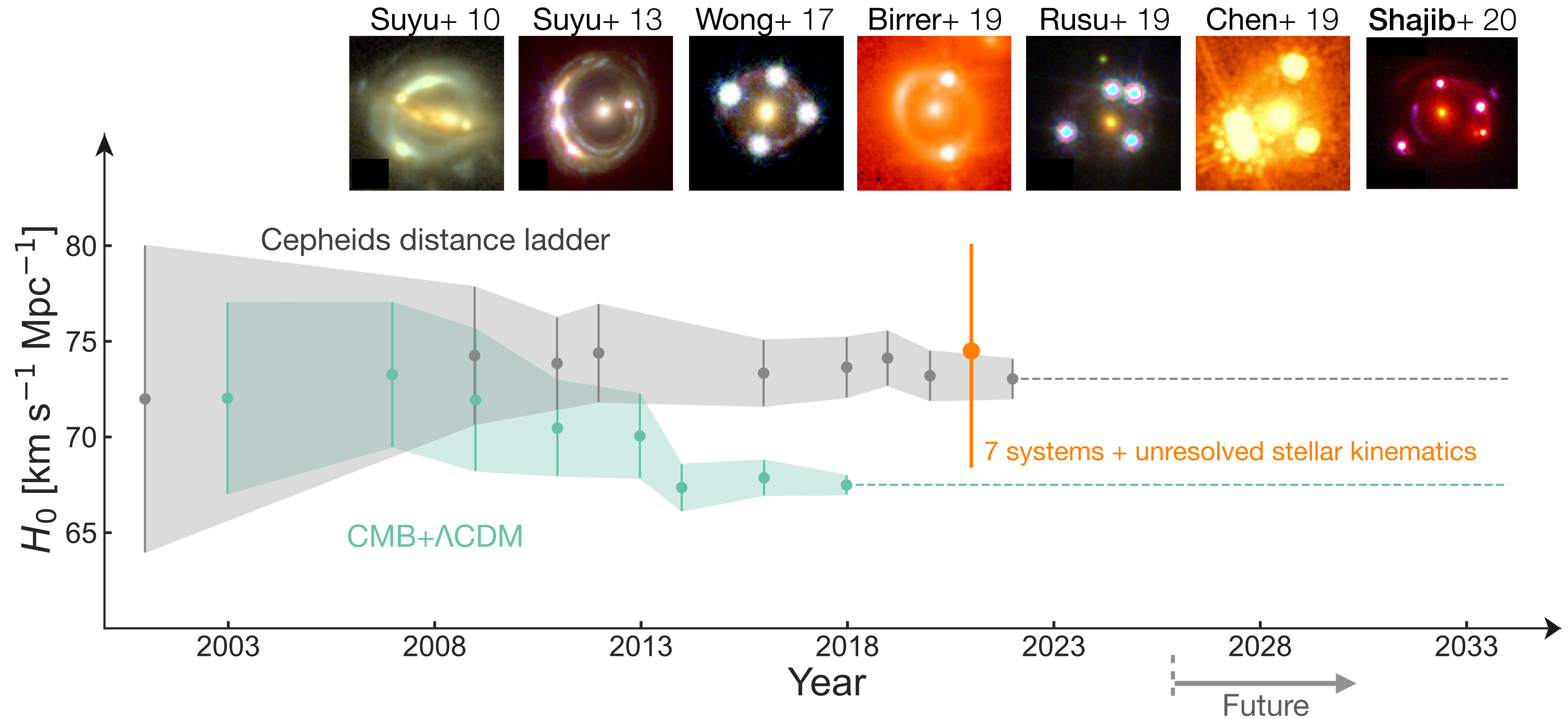
If the true mass profile is not a power law,
then H_0 would be biased.

Mass-sheet degeneracy (MSD) in lensing

$$\Sigma \rightarrow \Sigma' = \lambda \Sigma + (1 - \lambda)$$

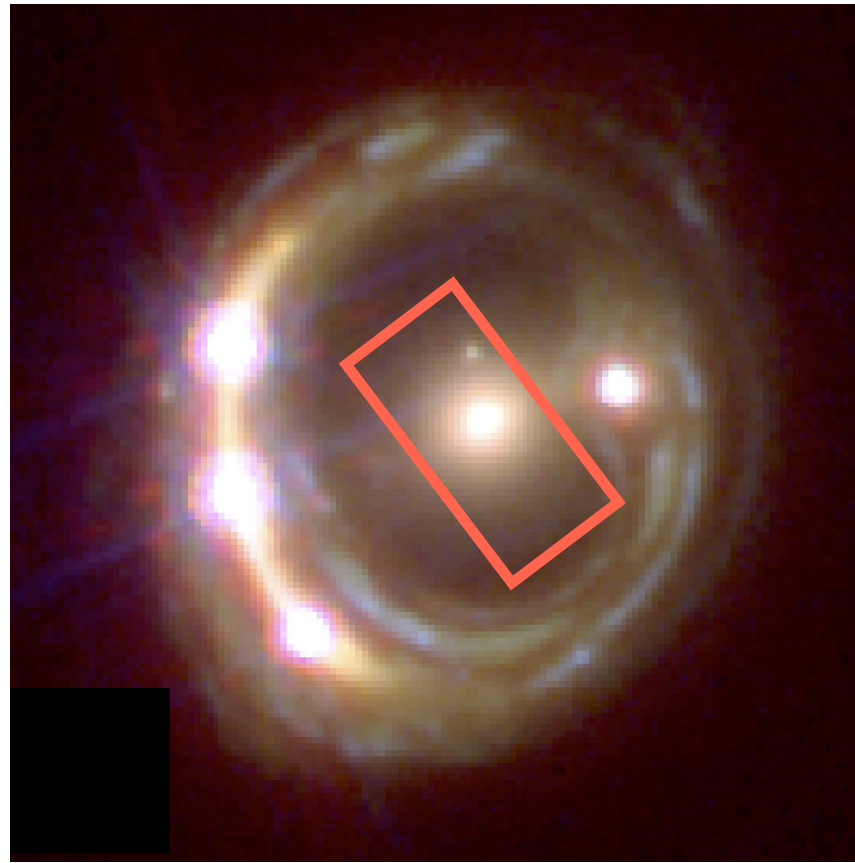


In 2020, the TDCOSMO collaboration measured H_0 **blindly** to 8% from 7 systems with the mass-sheet degeneracy constrained using kinematics.



Planck 18; Riess+ 22; Birrer, **Shajib**+ 20

But unresolved velocity dispersion brings it's own problem



Mass model

$$\rho(r) \approx r^{-\gamma}$$

Anisotropy model

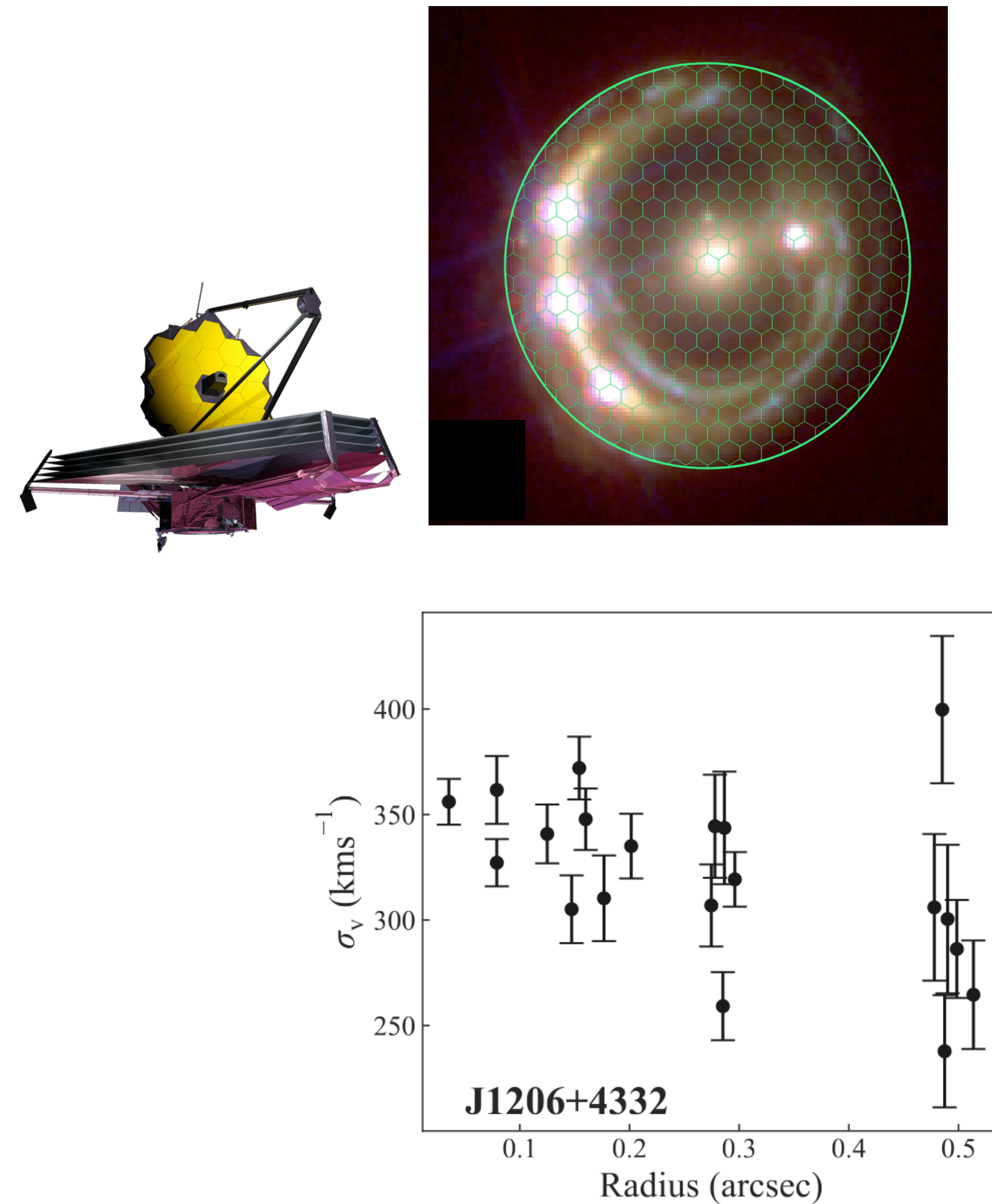
$$b = 1 - \frac{\sigma_z}{\sigma_R}$$

$$\frac{\zeta (b\overline{v_z^2} - \overline{v_\phi^2})}{R} + \frac{\partial (b\zeta \overline{v_z^2})}{\partial R} = -\zeta \frac{\partial \Phi}{\partial R}$$

$$\frac{\partial (\zeta \overline{v_z^2})}{\partial z} = -\zeta \frac{\partial \Phi}{\partial z},$$

Introduce Mass-Anisotropy degeneracy

Resolved velocity dispersion breaks both MSD and MAD



Mass model

$$\rho(r) \approx r^{-\gamma}$$

Anisotropy model

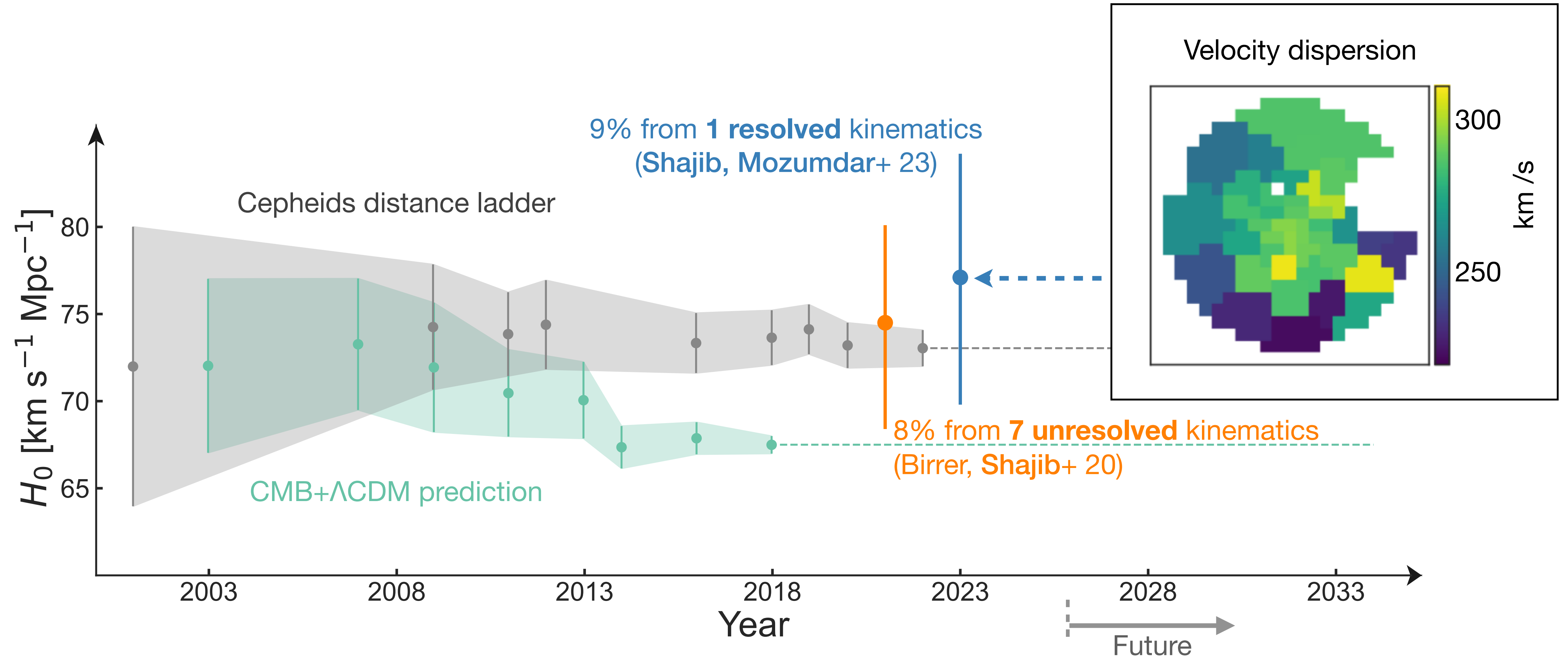
$$b = 1 - \frac{\sigma_z}{\sigma_R}$$

$$\frac{\zeta (b\overline{v_z^2} - \overline{v_\phi^2})}{R} + \frac{\partial (b\zeta \overline{v_z^2})}{\partial R} = -\zeta \frac{\partial \Phi}{\partial R}$$

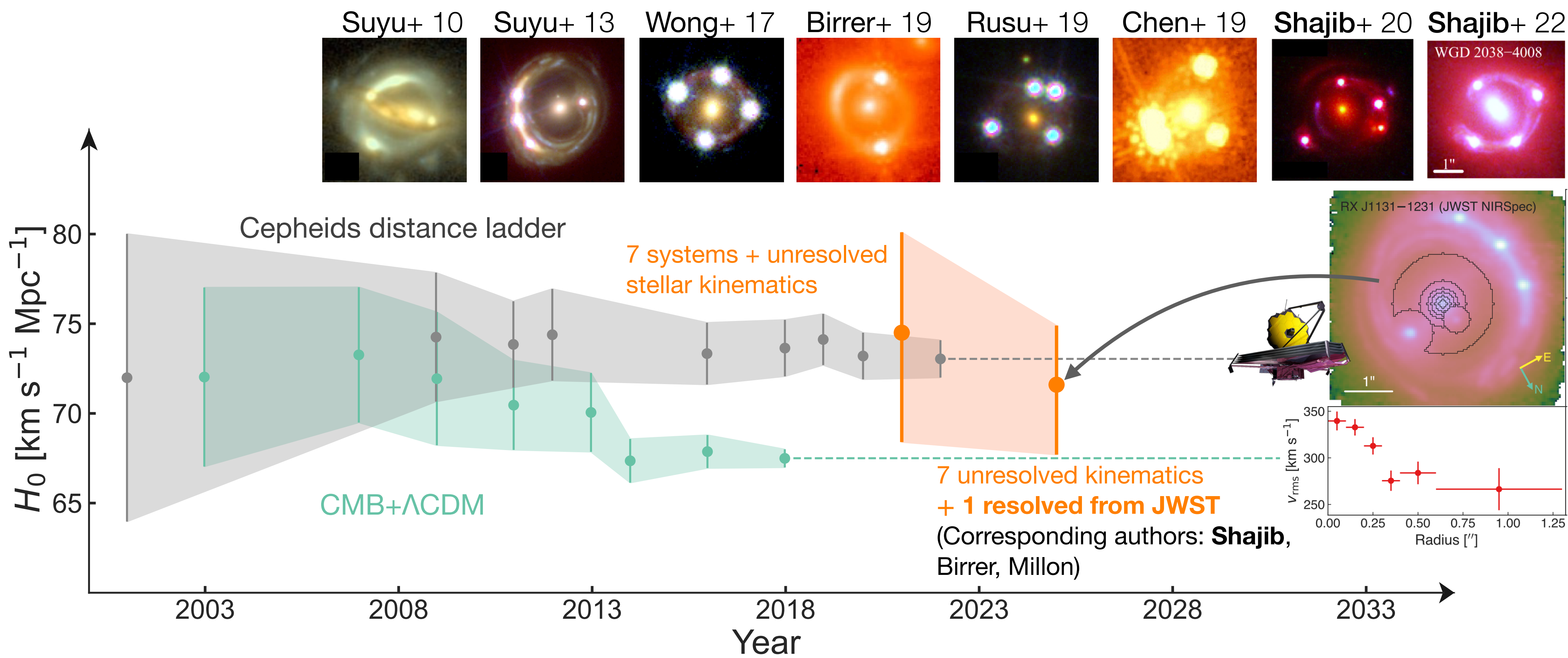
$$\frac{\partial (\zeta \overline{v_z^2})}{\partial z} = -\zeta \frac{\partial \Phi}{\partial z},$$

~~Mass-Anisotropy degeneracy (MAD)~~

Spatially resolved stellar kinematics constrain H_0 to 9% from only one time-delay lens.



In 2025, the TDCOSMO collaboration measured H_0 **blindly** to 5% from 8 systems with the mass-sheet degeneracy constrained using kinematics.



Planck 18; Riess+ 22; **TDCOSMO Collaboration 2025**

Improving systematic error budget:

$$G_{\text{mod}}(\ln\lambda) = \sum_{n=1}^N w_n \left\{ [T_n(\ln\lambda) * \mathcal{L}_n(c\ln\lambda)] \sum_{k=1}^K a_k \mathcal{P}_k(\ln\lambda) \right\} + \sum_{l=0}^L b_l \mathcal{P}_l(\ln\lambda) + \sum_{j=1}^J c_j S_j(\ln\lambda)$$

Model spectra

Wavelength

Template

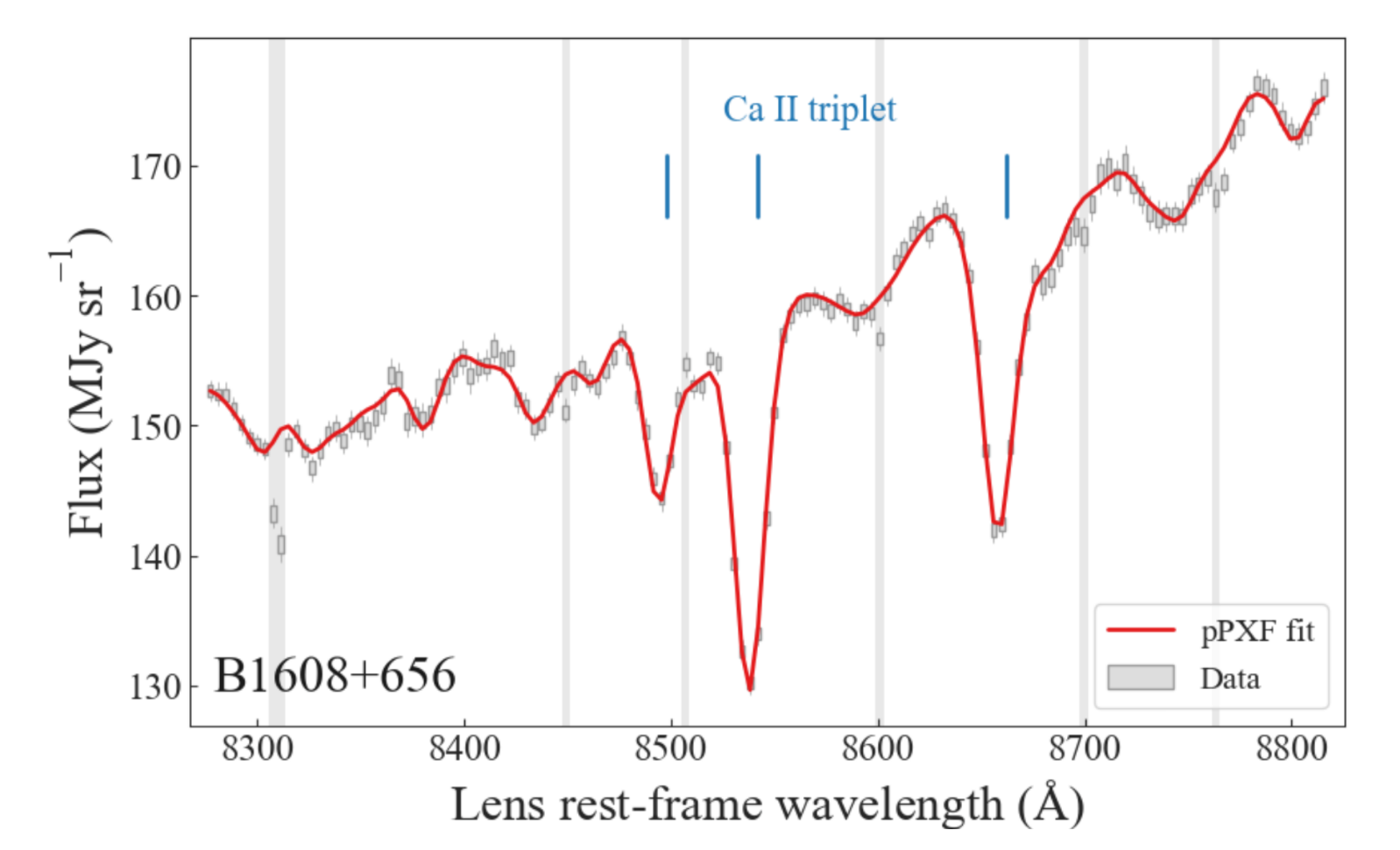
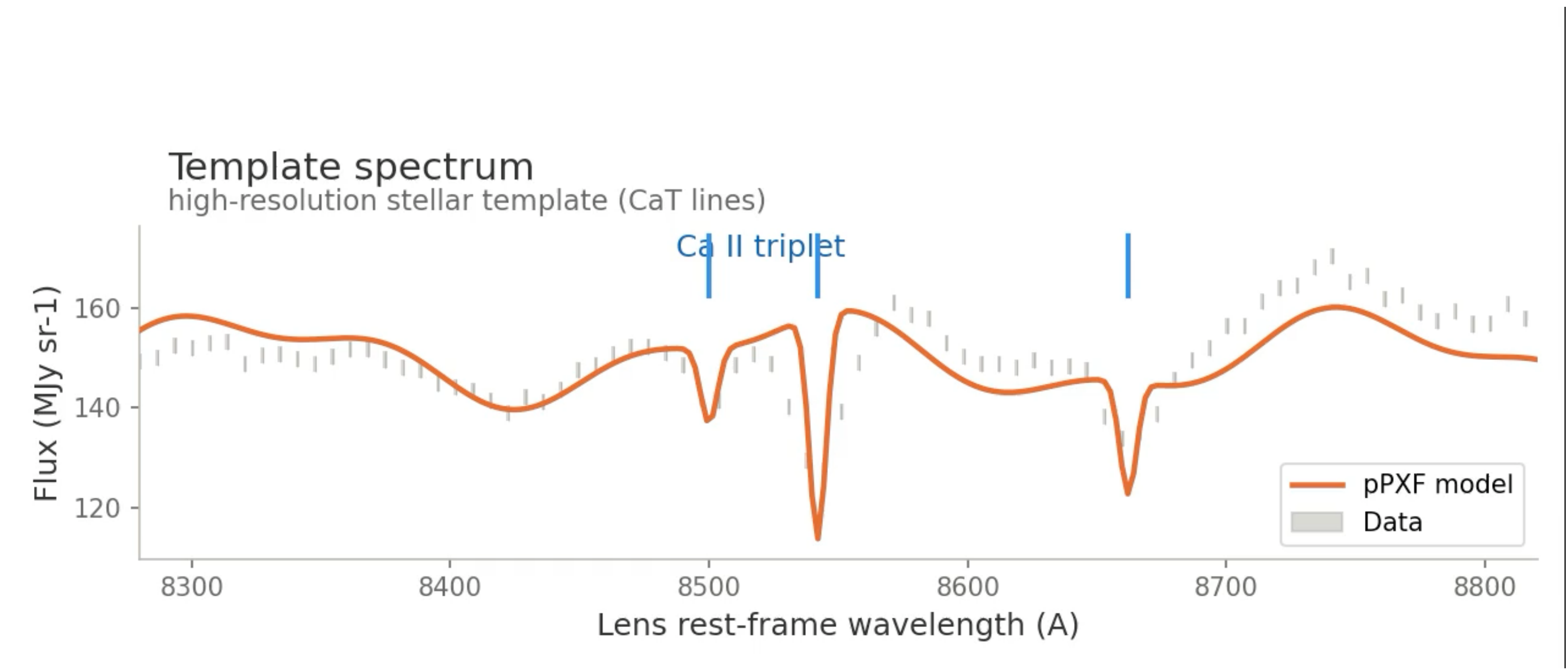
Instrument LSF

Multiplicative polynomial

Additive polynomial

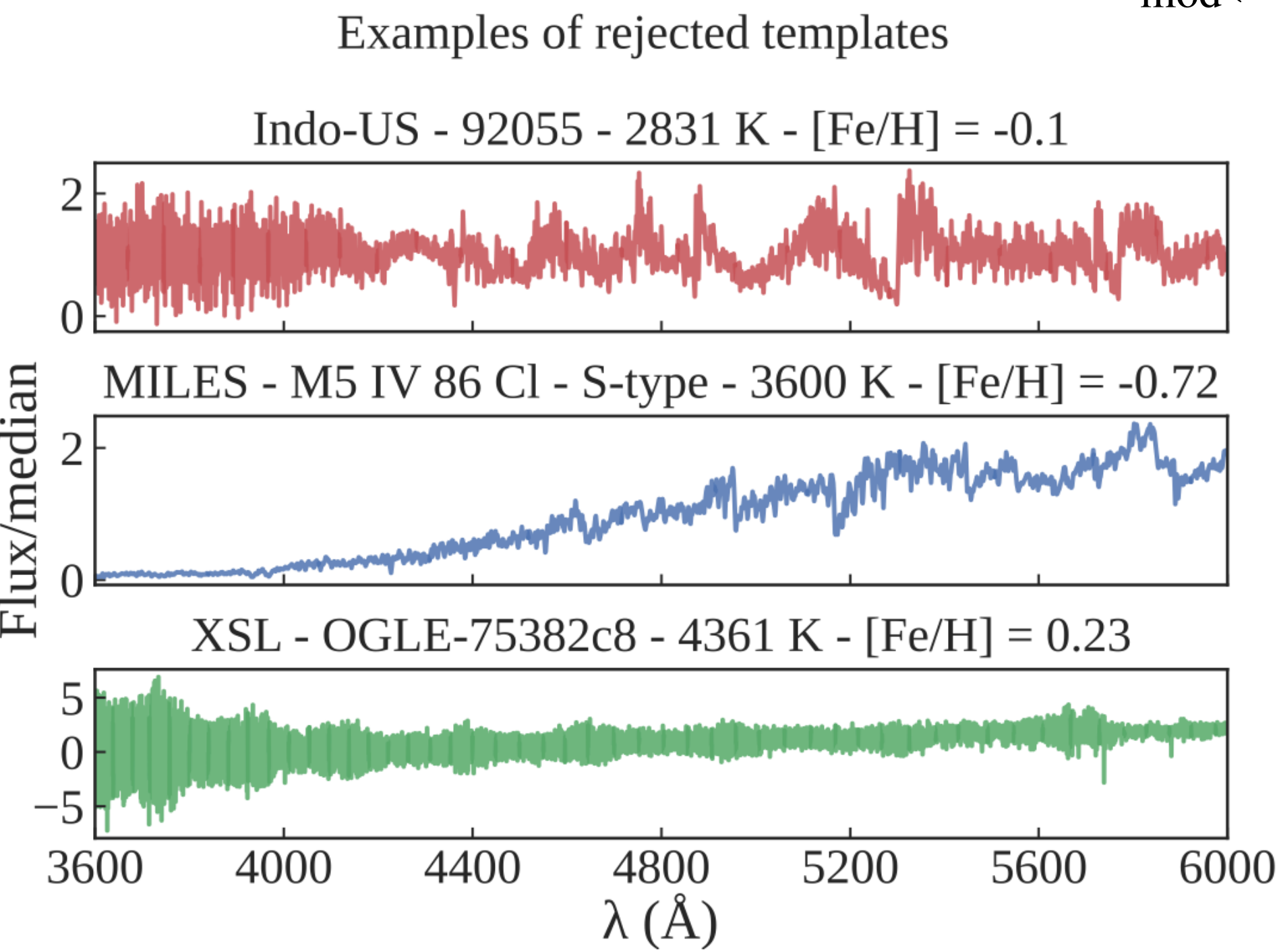
Background

pPXF fit

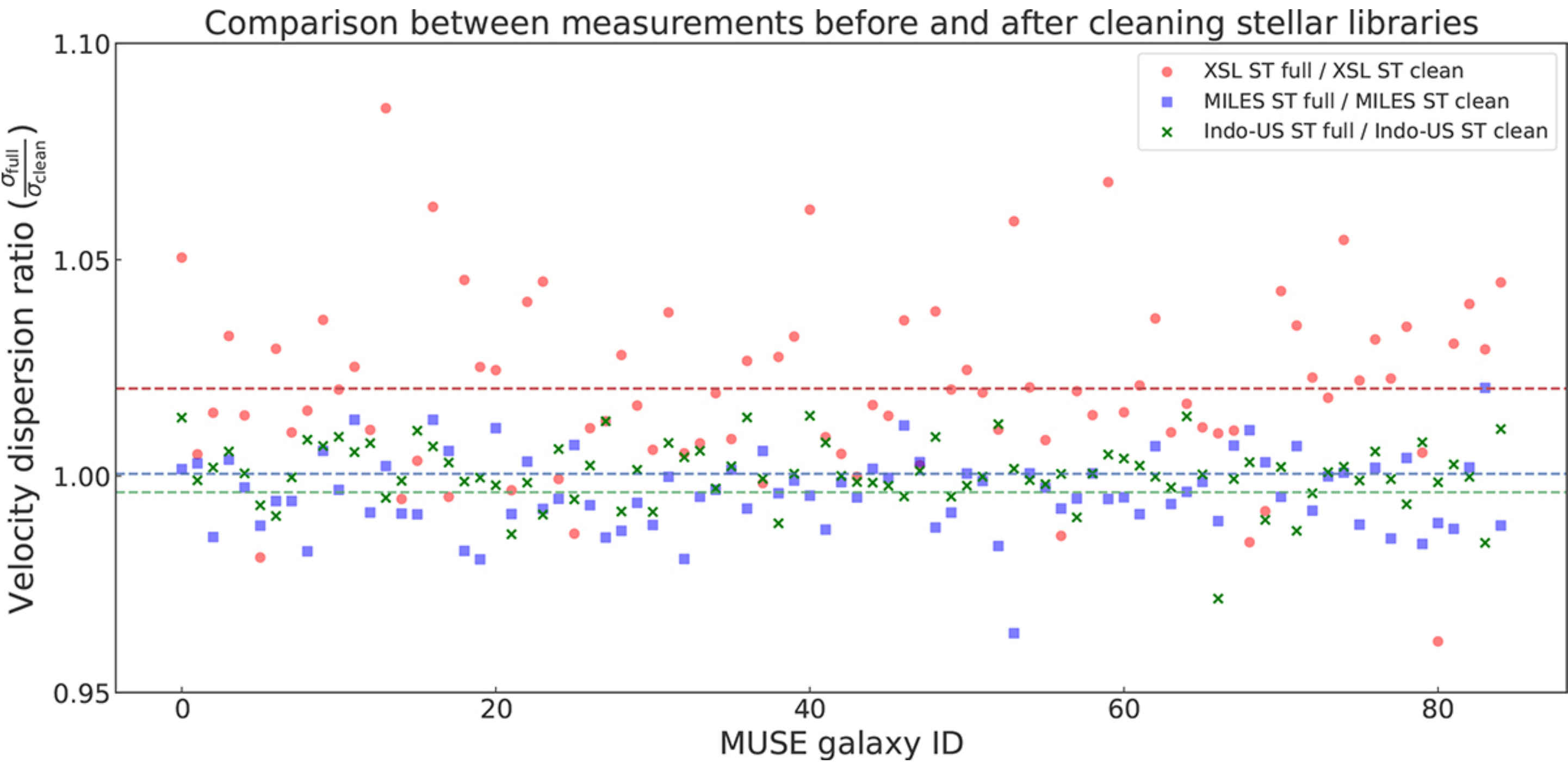


Bad templates provide bias fits:

$$G_{\text{mod}}(\ln\lambda) = \sum_{n=1}^N w_n \left\{ [T_n(\ln\lambda) * \mathcal{L}_n(c\ln\lambda)] \sum_{k=1}^K a_k \mathcal{P}_k(\ln\lambda) \right\} + \sum_{l=0}^L b_l \mathcal{P}_l(\ln\lambda) + \sum_{j=1}^J c_j S_j(\ln\lambda)$$



Step	# MILES	# XSL	# Indo-US
Initial	985	830	1273
After library authors' cuts ^(a)	801	530	1273
With T_{eff} and Fe/H ^(b)	790	522	1006
After a visual inspection	789	496	992



Use ‘cleaned’ stellar library

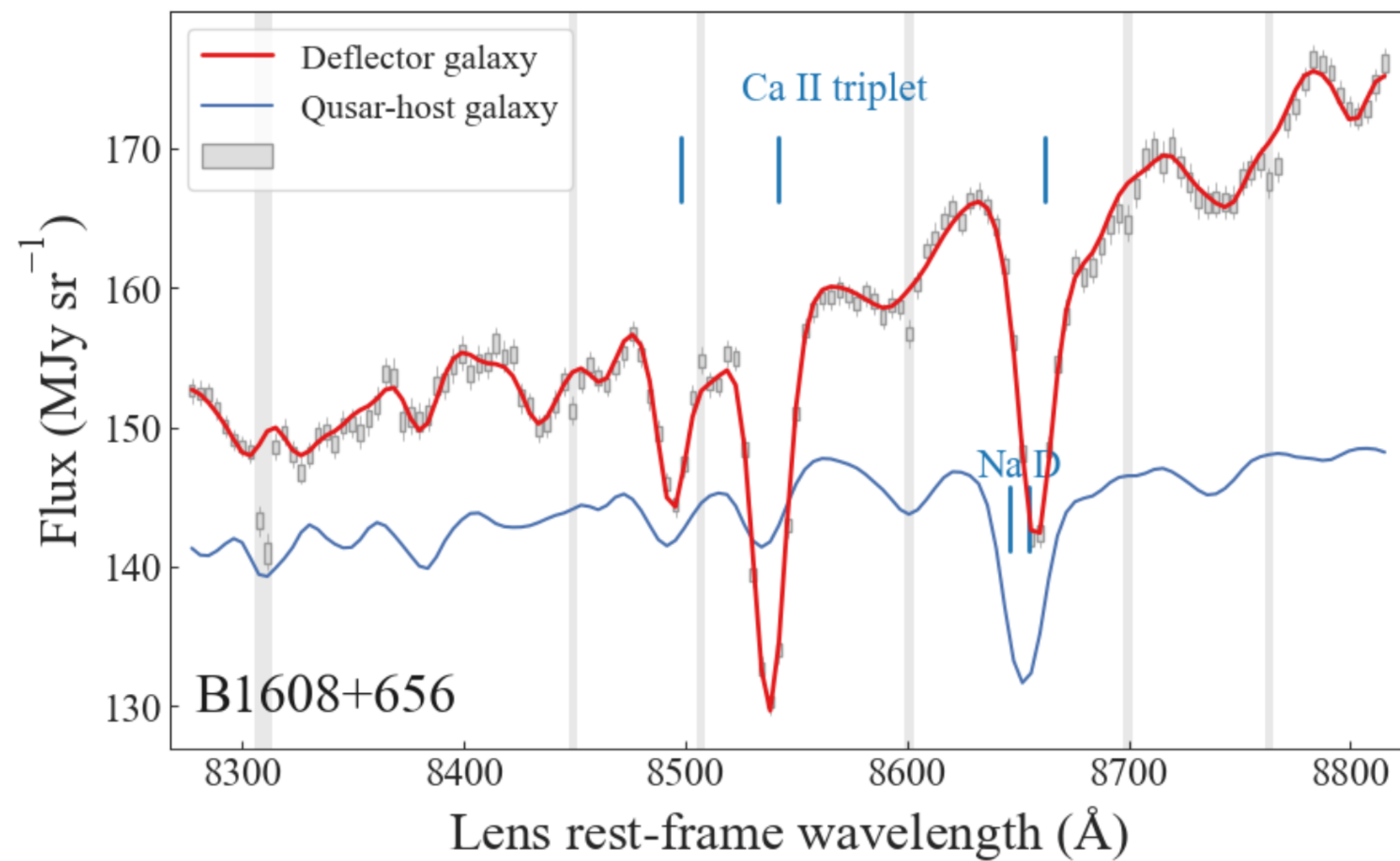
Marginalize measurements from all template libraries using Bayesian Information Criterion (BIC)

(Knabel & Mozumdar+2025)

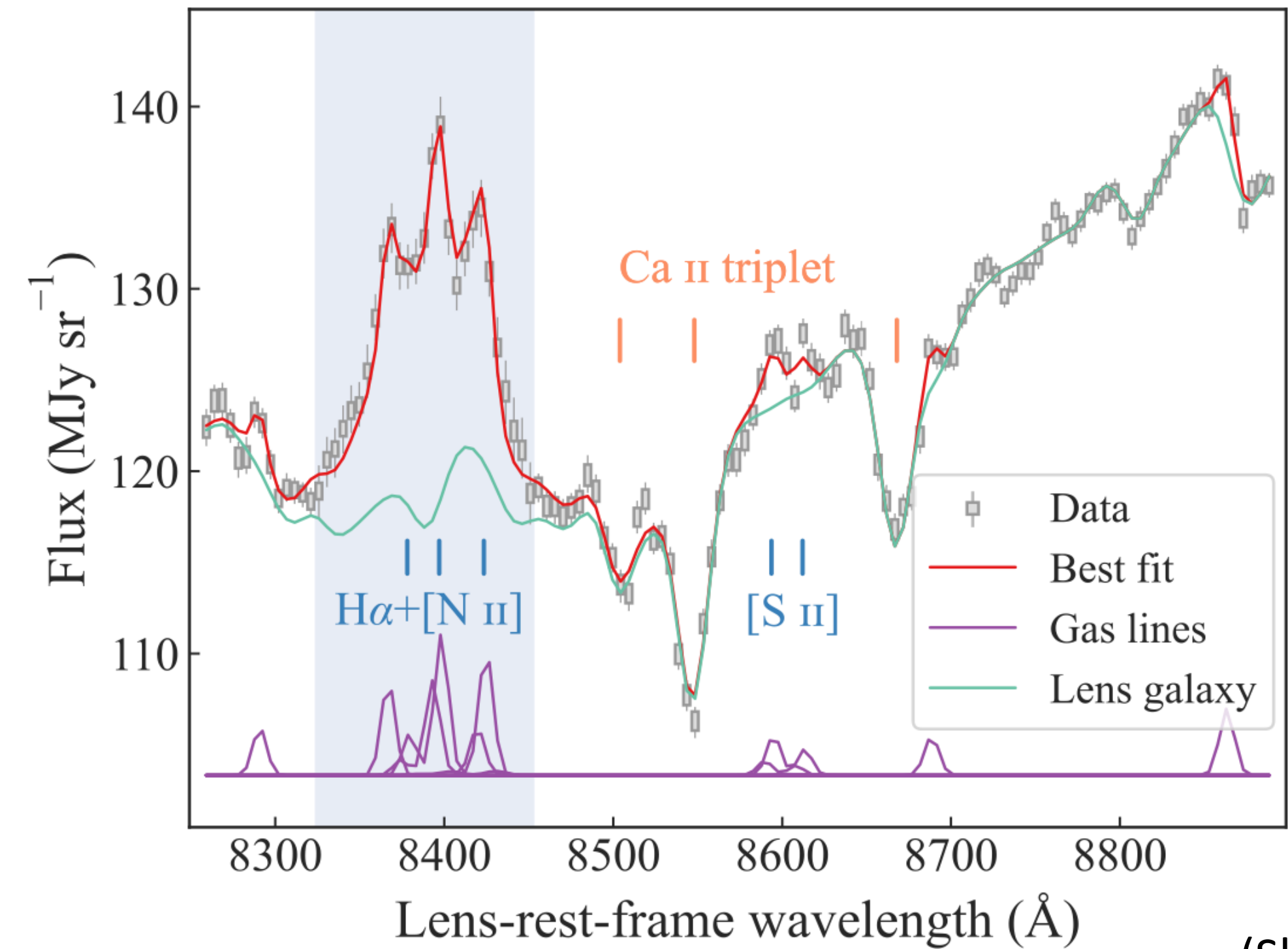
Improving systematic error budget:

$$G_{\text{mod}}(\ln\lambda) = \sum_{n=1}^N w_n \left\{ [T_n(\ln\lambda) * \mathcal{L}_n(c\ln\lambda)] \sum_{k=1}^K a_k \mathcal{P}_k(\ln\lambda) \right\} + \sum_{l=0}^L b_l \mathcal{P}_l(\ln\lambda) + \sum_{j=1}^J c_j S_j(\ln\lambda)$$

Observed spectra = Lens galaxy + Quasar-host galaxy + Quasar image



(Mozumdar+ 2026, inpreparation)



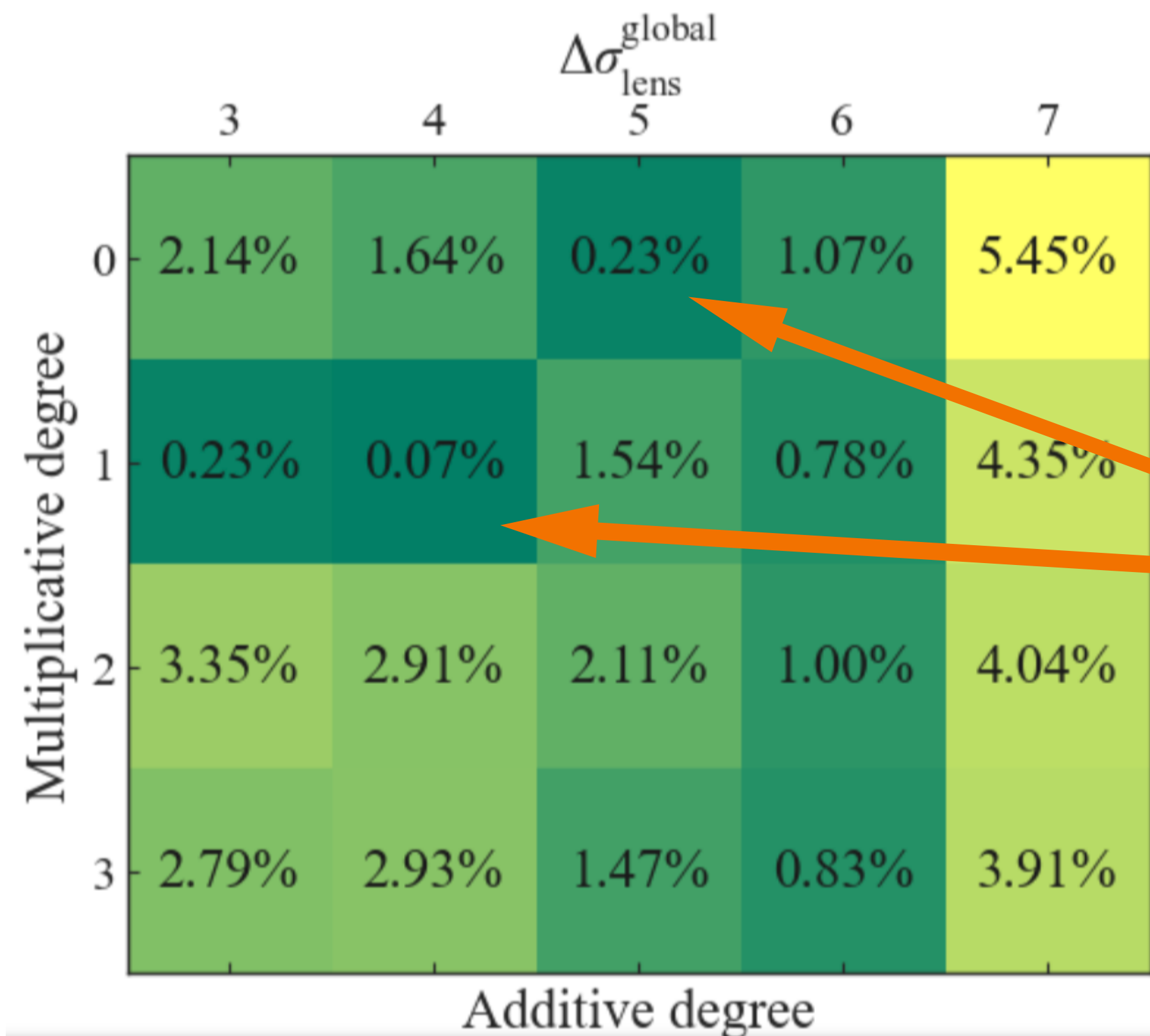
(Shajib+ 2026)

Include all three components in the pPXF fit

Improving systematic error budget:

$$G_{\text{mod}}(\ln\lambda) = \sum_{n=1}^N w_n \left\{ [T_n(\ln\lambda) * \mathcal{L}_n(c\ln\lambda)] \sum_{k=1}^K a_k \mathcal{P}_k(\ln\lambda) \right\} + \sum_{l=0}^L b_l \mathcal{P}_l(\ln\lambda) + \sum_{j=1}^J c_j S_j(\ln\lambda)$$

Polynomial order grid



In a prefect world, measurement from different template libraries should be same.

The optimal polynomial degree pair minimizes the scatter among measurements using different stellar libraries

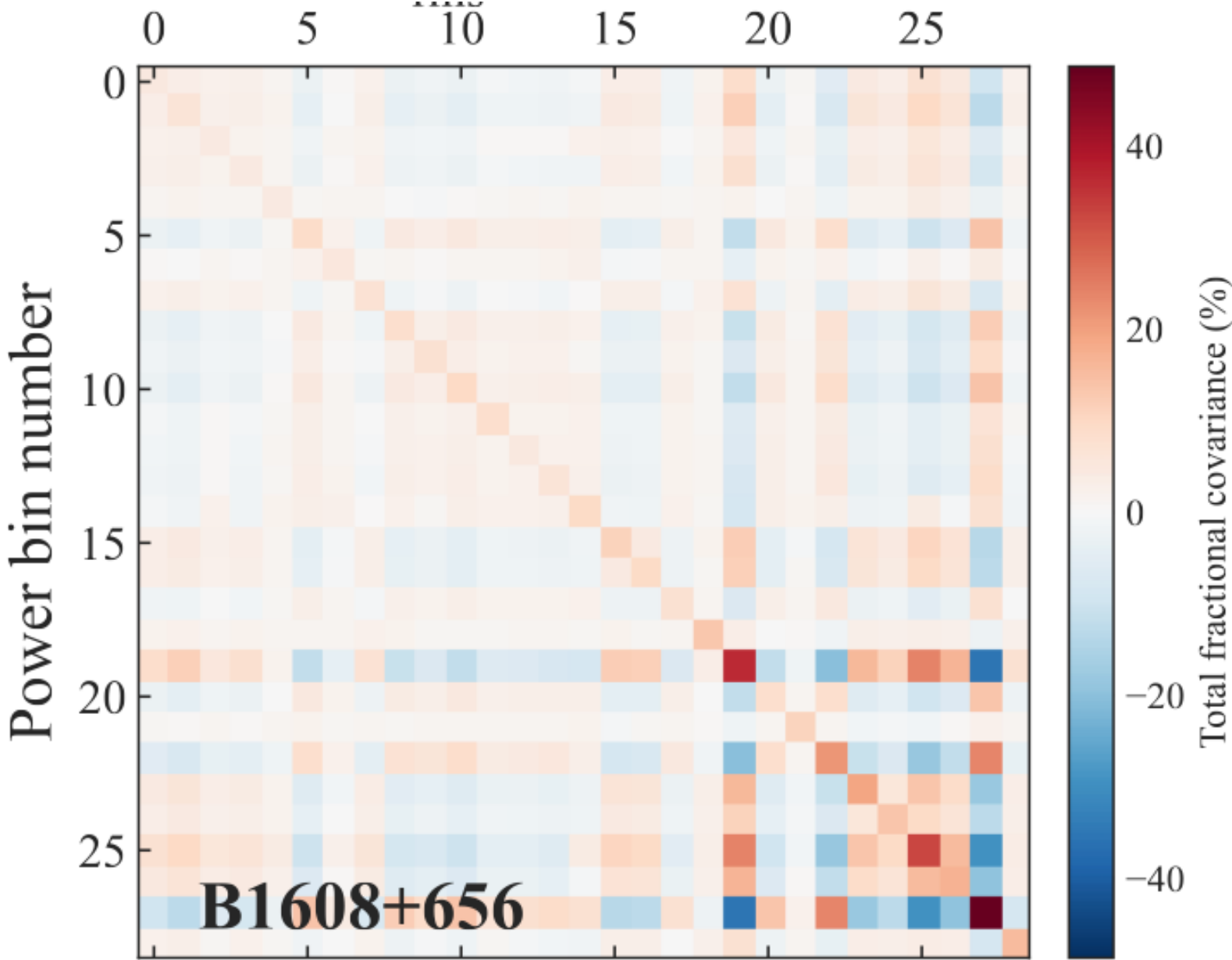
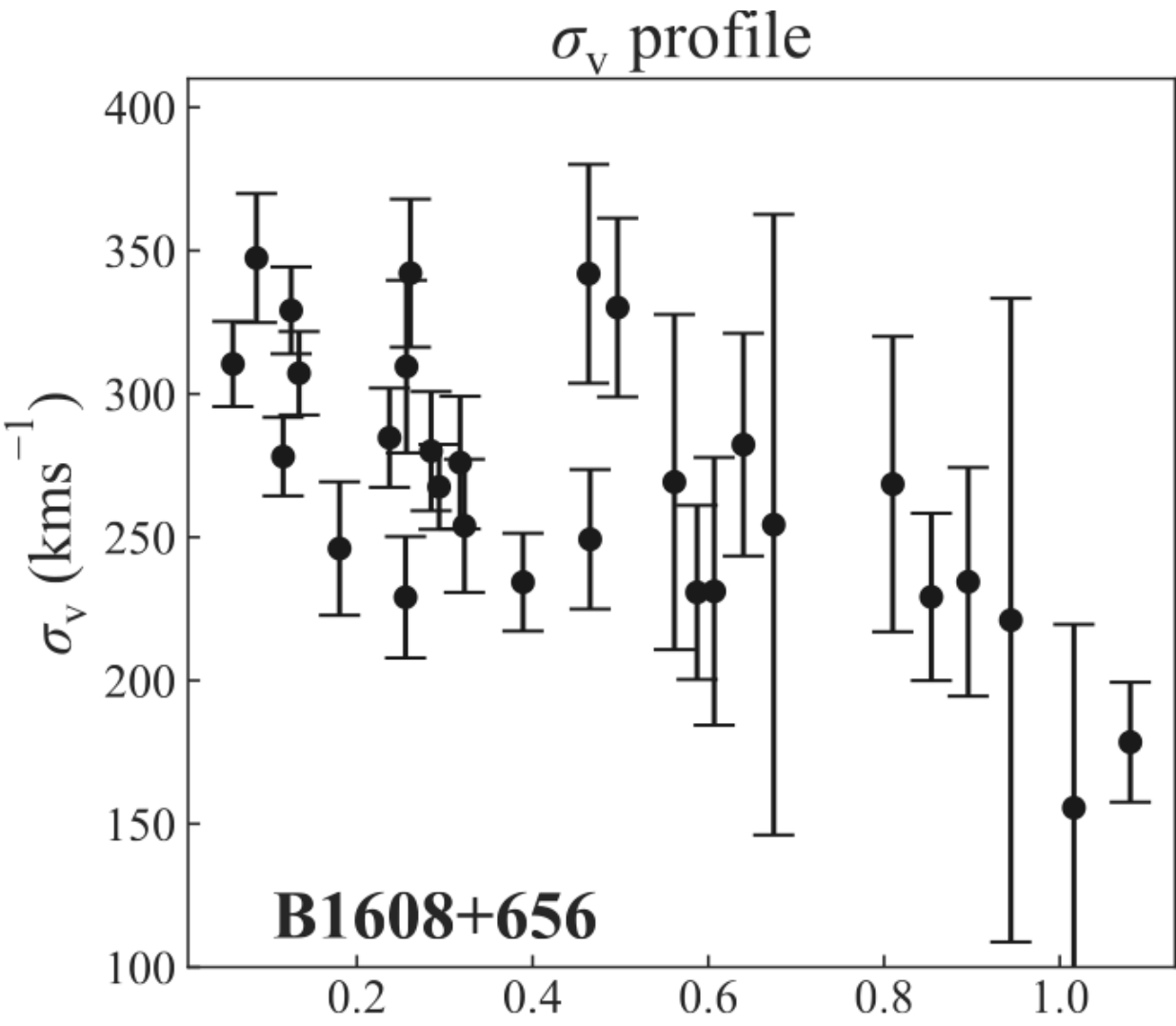
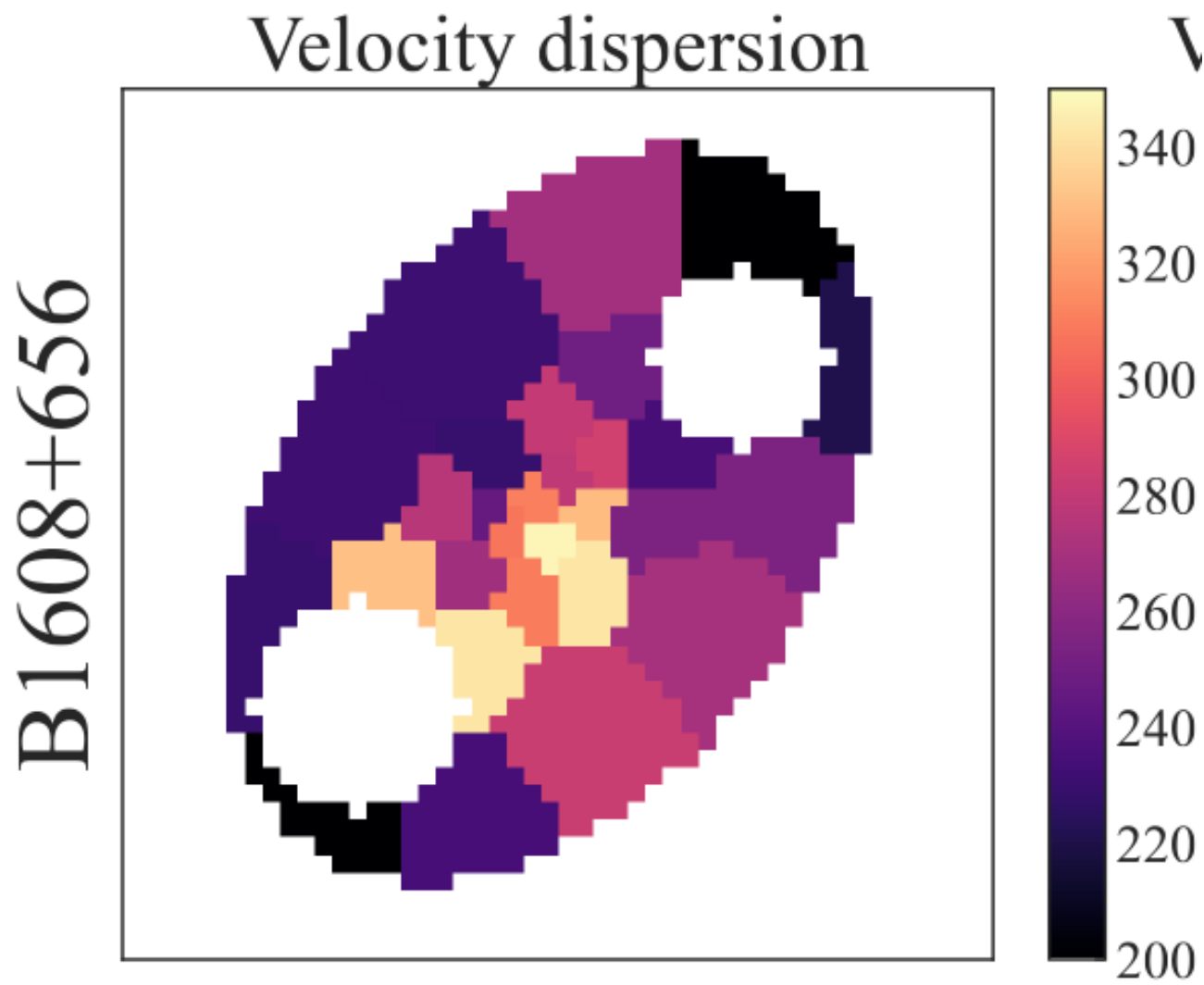
Improving systematic error budget:

$$G_{\text{mod}}(\ln\lambda) = \sum_{n=1}^N w_n \left\{ [T_n(\ln\lambda) * \mathcal{L}_n(c\ln\lambda)] \sum_{k=1}^K a_k \mathcal{P}_k(\ln\lambda) \right\} + \sum_{l=0}^L b_l \mathcal{P}_l(\ln\lambda) + \sum_{j=1}^J c_j S_j(\ln\lambda)$$

systematic source	choices
template library	Indo-US, XSL
polynomial degree ($a_{\text{deg}}, m_{\text{deg}}$)	B1608+656: [(0,4), (1,3), (1,6), (0,5)] J1206+4332: [(1,4), (2,6), (1,6), (0,5)]
outlier rejection threshold	$2.50\sigma, 2.70\sigma$

16 combination of systemic choice

Covariance Matrix

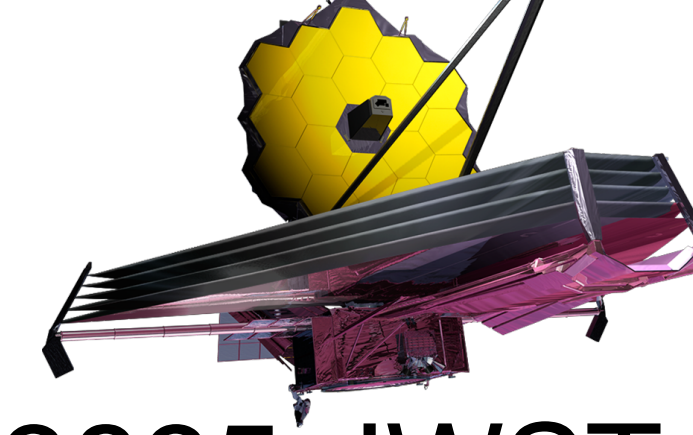


(Mozumdar+ 2026, in preparation)

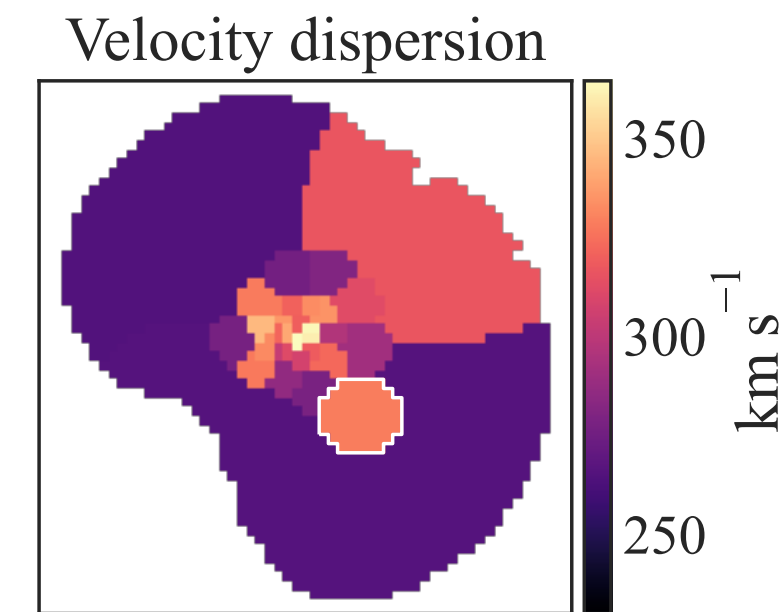
Improving random error budget:

- Increase sample size with resolved kinematics -

TDCOSMO 2025: **1** JWST/IFU lens



TDCOSMO 2025 JWST-IFU Sample



RXJ1131-1231

Shajib+2026

Improving random error budget:

- Increase sample size with resolved kinematics -

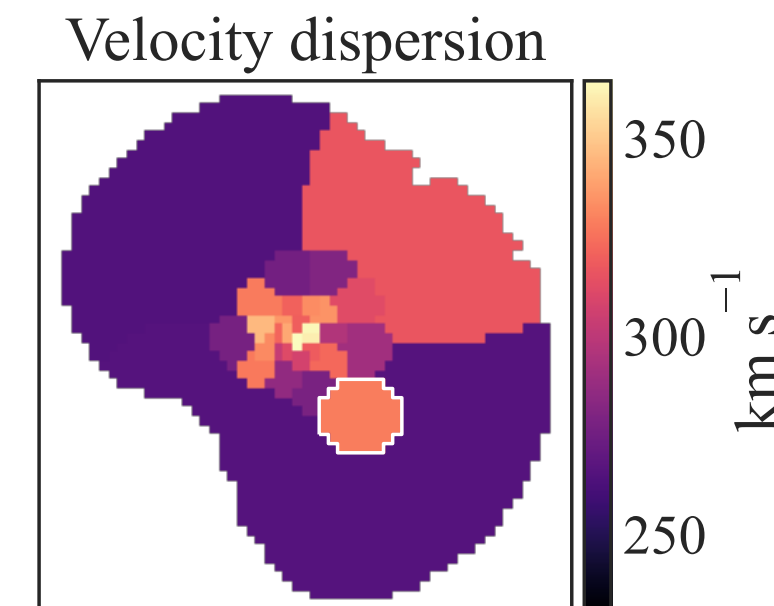
TDCOSMO 2025: **1** JWST/IFU lens

TDCOSMO 2026: **6** JWST/IFU lens

TDCOSMO 2026+: **16** JWST/IFU lens

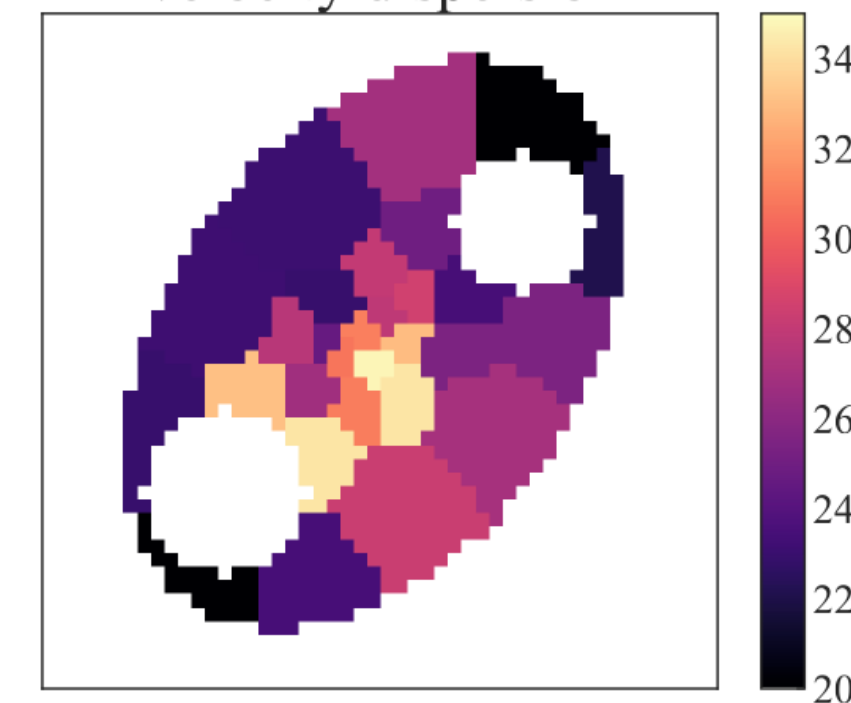


TDCOSMO 2026 JWST-IFU Sample

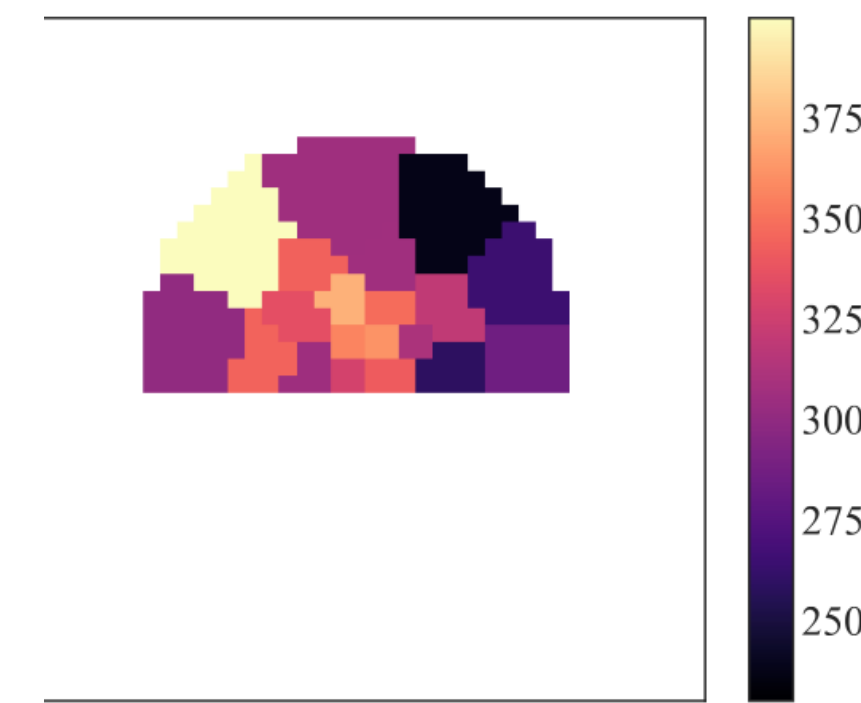


RXJ1131-1231

Shajib+2026

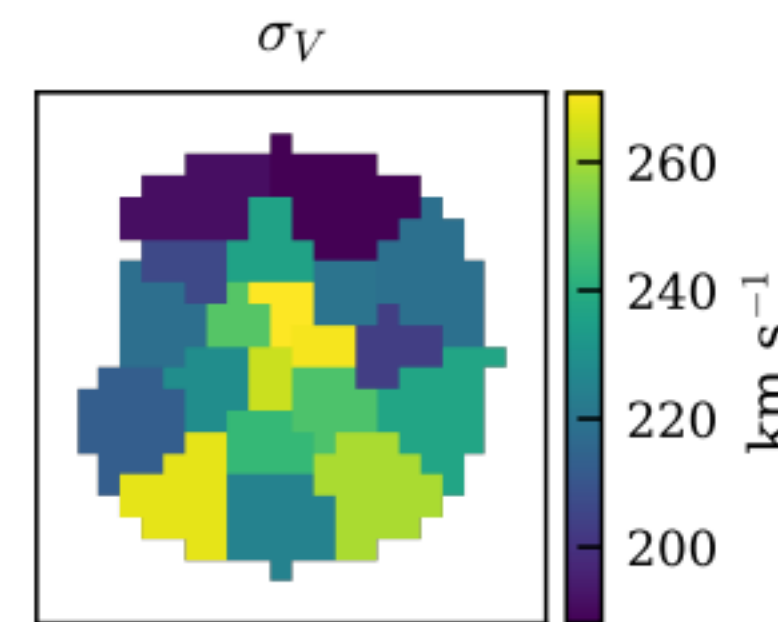


B1608+656

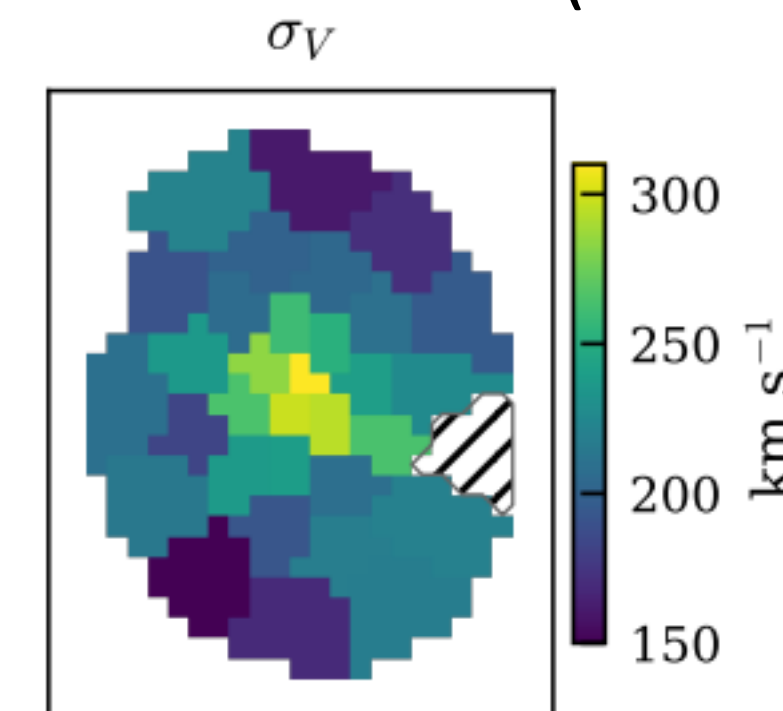


J1206+4332

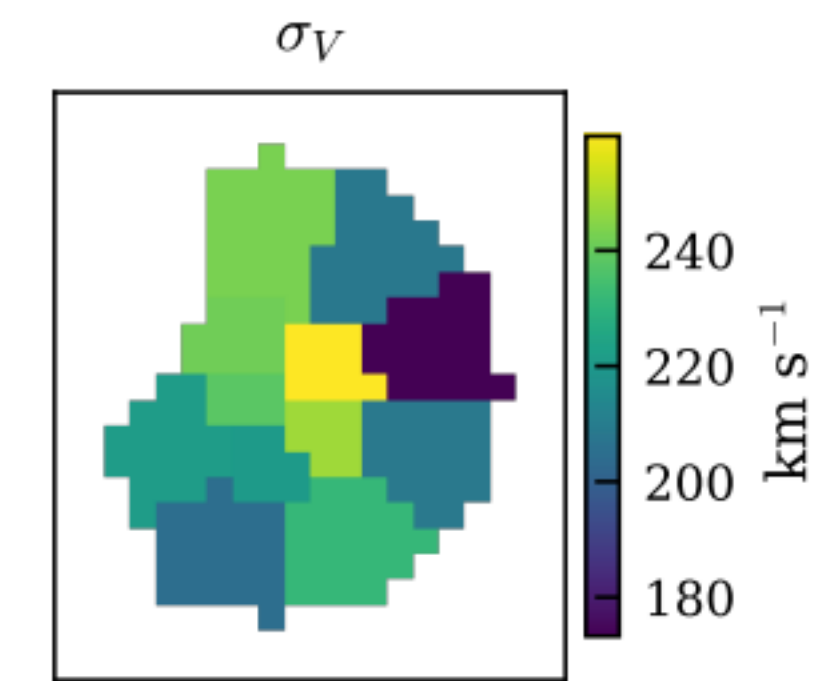
(Mozumdar+ 2026, in preparation)



HE0435-1223



PG1115+080



WFI2033-4723

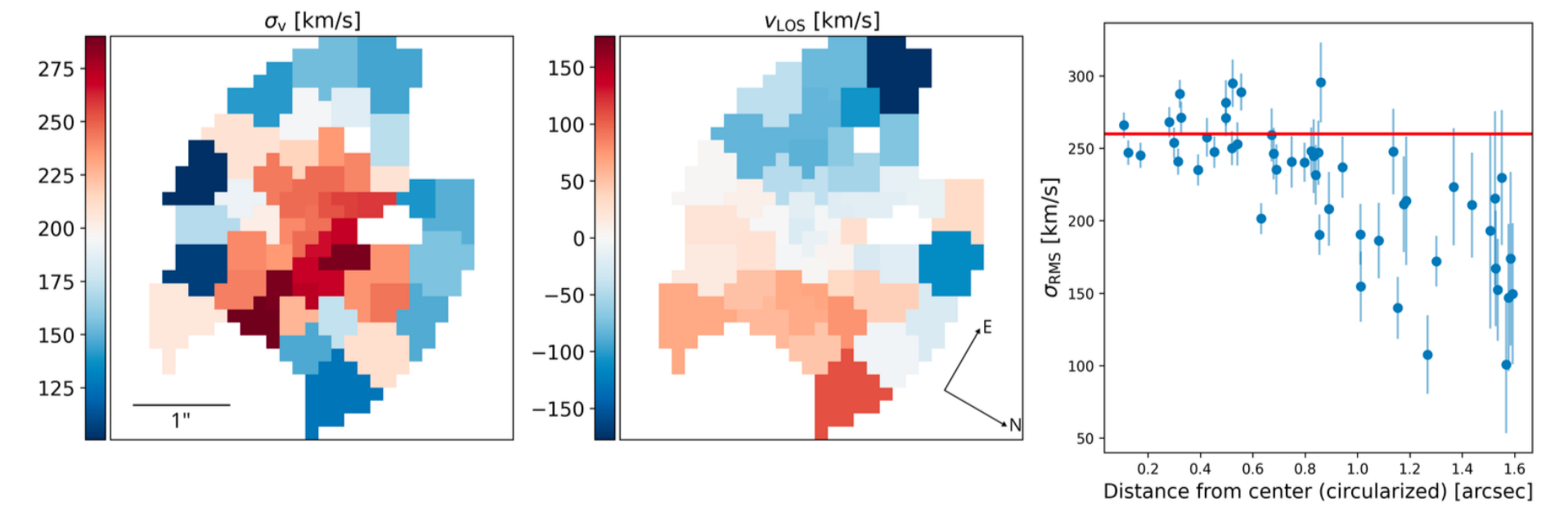
(Knabel+ 2026, in preparation)

We need perfect reduction of NIRSspec data cube - Check Shawn's talk tomorrow

Improving random error budget:

Ground based IFU (Keck-KCWI and VLT/MUSE)

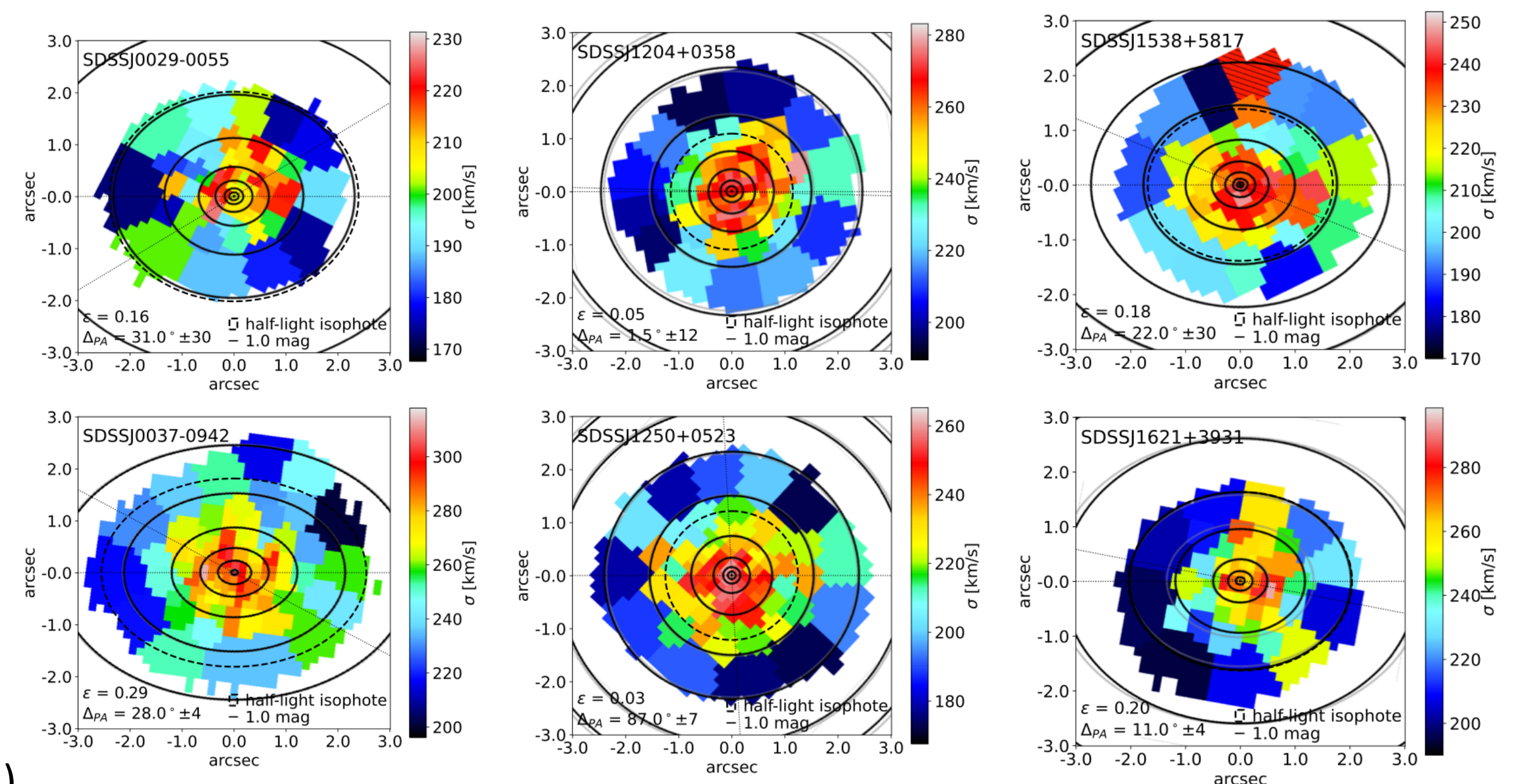
TDCOSMO 2026 - 3 KCWI/MUSE IFU



J1433+6007

Sheu+2026

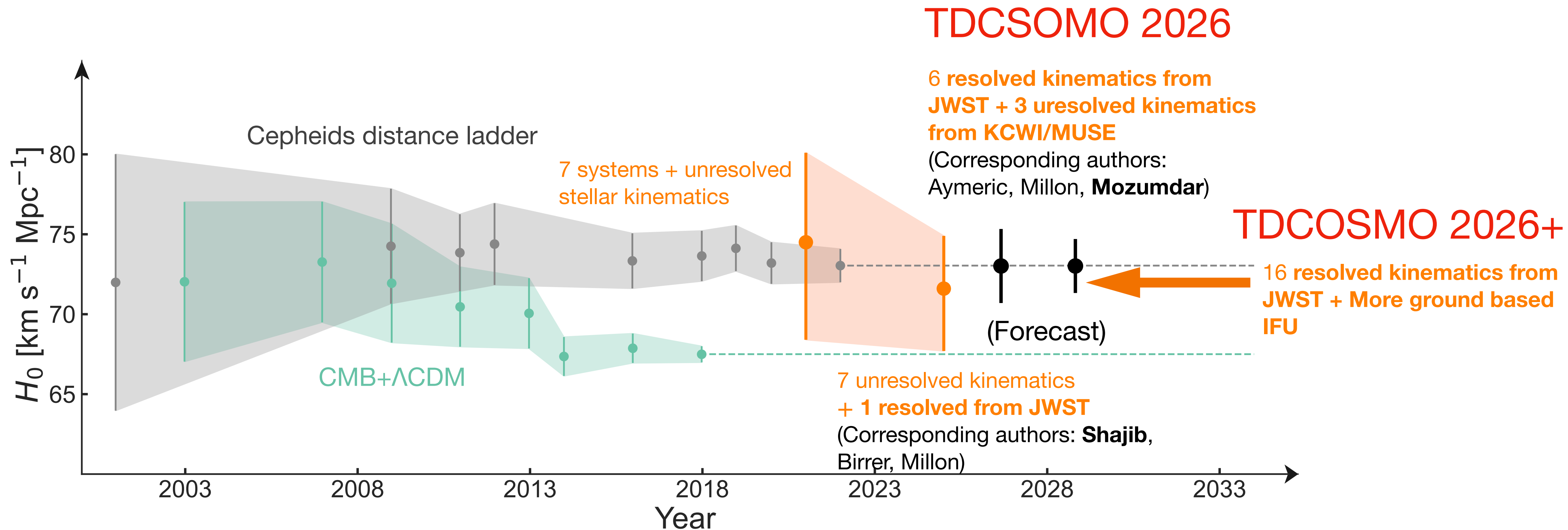
External dataset - SLACS and SL2S



(Knabel+ 2025)

Improving precision on H_0 to 2% level:

TDCOSMO 2026 is almost here - stay tuned !



Planck 18; Riess+ 22; **TDCOSMO Collaboration**

Summary :

- Precision kinematics is integral for precision H_0 via time-delay cosmography, without any mass profile assumption.
- Resolved kinematics is most effective to alleviate both mass-sheet degeneracy (MSD) and mass-anisotropy degeneracy (MAD).
- We can control systematic uncertainty to $\sim 1\%$ level.
- We are improving random error budget by increasing sample size with JWST-IFU kinematics and ground based IFU kinematics.
- Time-delay cosmography can provide $\sim 2\%$ H_0 , with 16 JWST based IFU data and plus other IFU and complementary datasets.